

Mechanics of Nanowires

Introduction to Nanomechanics - Fall 2021

$$S_F = 4 k_B T \Gamma$$

$$\Gamma = \frac{m\omega_0}{Q} \quad \frac{dE}{dt} = -\Gamma \dot{x}^2$$

$$m \propto wtl \quad \omega_0 \propto \frac{t}{l^2} \quad Q \propto t$$

$$\Gamma \propto \frac{wt}{l}$$

Scale all lengths by β :

$$\Gamma \propto \beta \quad \omega_0 \propto \beta^{-1}$$

100 μm

A grayscale micrograph showing the corner of a thin, rectangular plate. The plate is oriented diagonally, with the corner pointing towards the bottom-left. The surface of the plate shows some texture and slight variations in tone. A white arrow points to the sharp corner of the plate. In the bottom-left corner, there is a white horizontal scale bar with the text "100 μm" above it.

Amplitude measurement:

$$F_{min} = \sqrt{4 k_B T \Gamma} \propto \sqrt{\frac{wt}{l}} \propto \beta^{1/2}$$

$$\tau_{min} = l_e \sqrt{4 k_B T \Gamma} \propto \sqrt{wtl} \propto \beta^{3/2}$$

Frequency measurement:

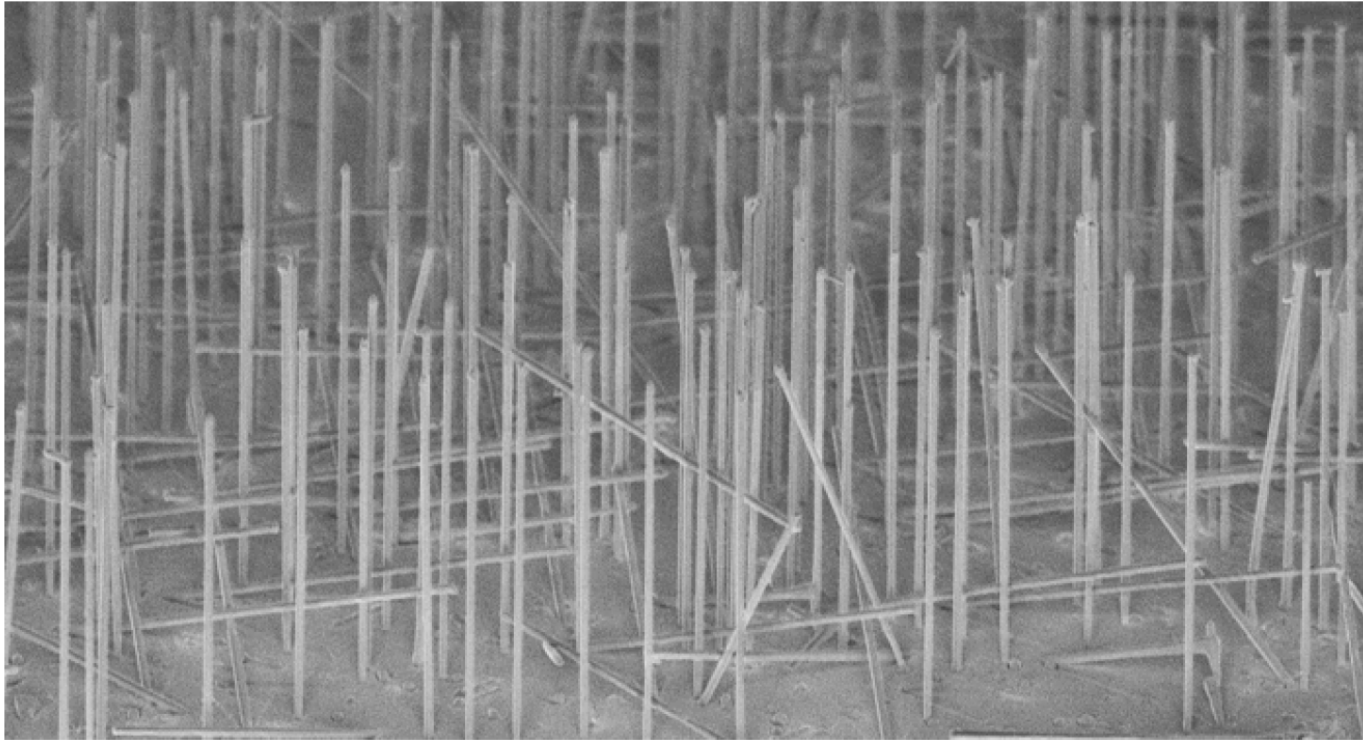
$$\left(\frac{\partial F}{\partial x}\right)_{min} = \frac{1}{x_{osc}} \sqrt{4 k_B T \Gamma} \propto \frac{wt^2}{l^2} \propto \beta$$

$$\left(\frac{\partial \tau}{\partial \theta}\right)_{min} = \frac{l_e}{\theta_{osc}} \sqrt{4 k_B T \Gamma} \propto wt^2 \propto \beta^3$$

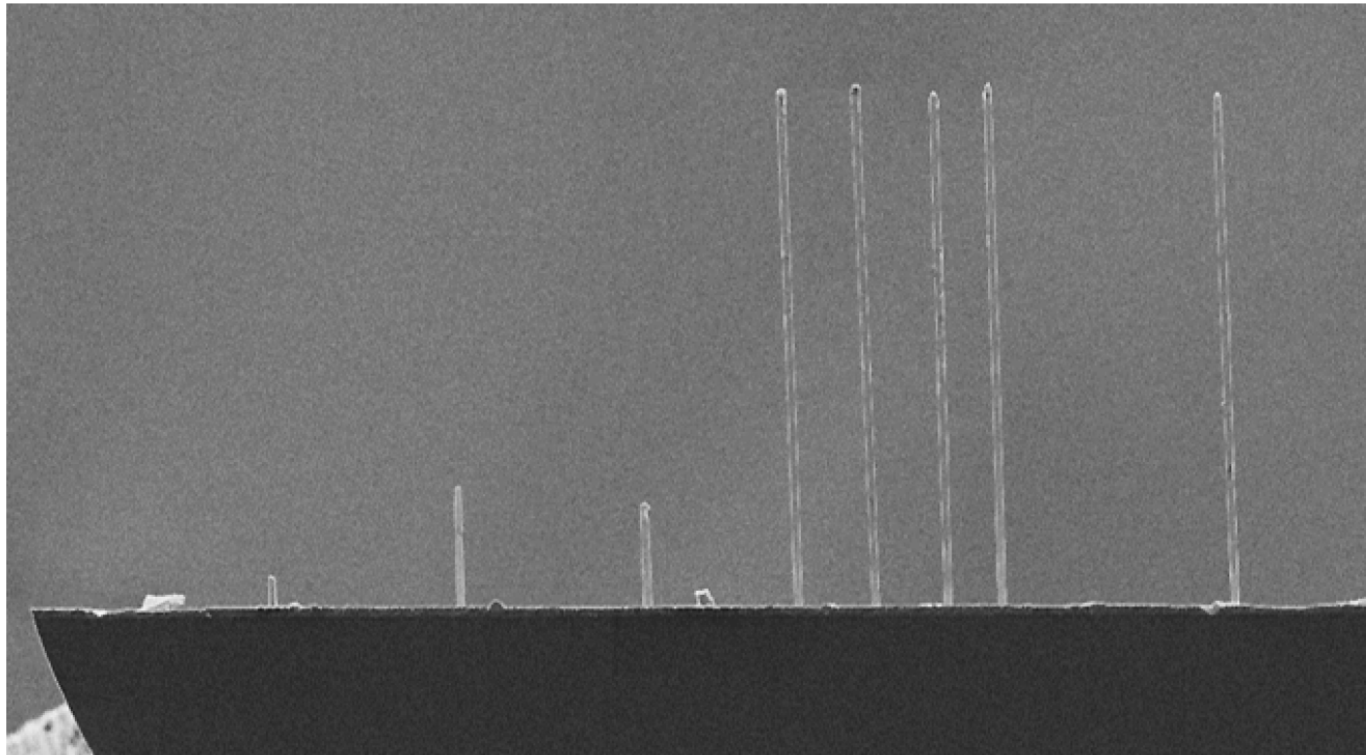
$$x_{th} = \sqrt{\frac{k_B T}{m \omega_0^2}} \propto \sqrt{\frac{l^3}{wt^3}} \propto \beta^{-1/2}$$

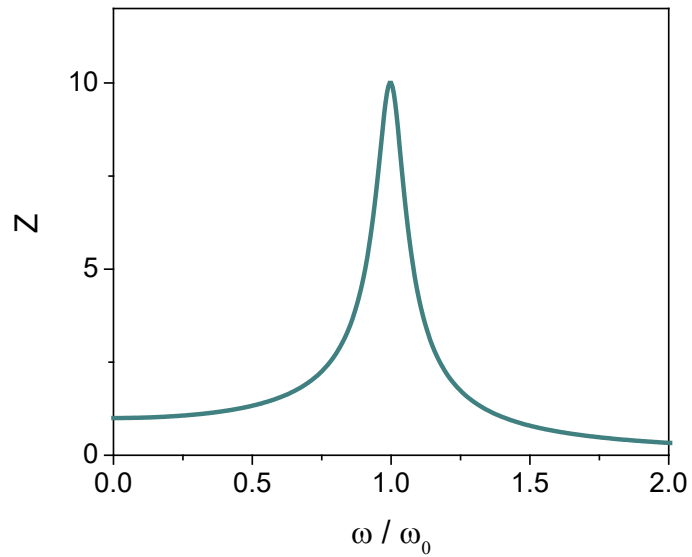
2 μ m

MBE-grown GaAs/AlGaAs nanowires



MBE-grown GaAs/AlGaAs nanowires





Equation of motion

$$\ddot{x}(t) + \gamma \dot{x}(t) + \omega_0 x(t) = F(t)$$

Duffing Equation

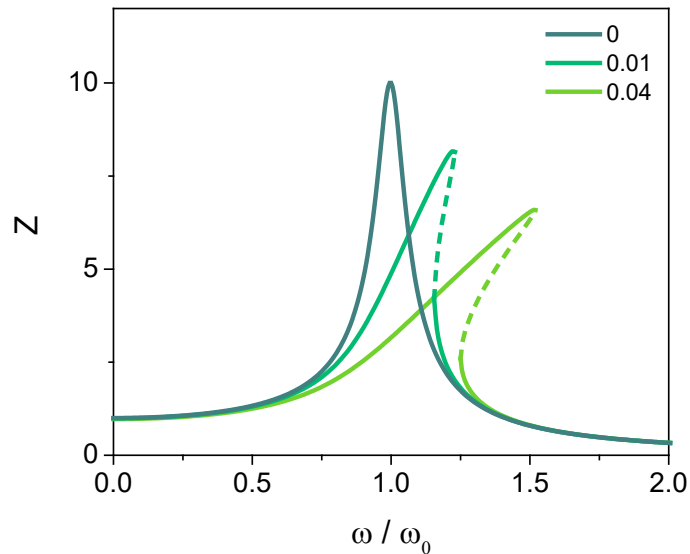
$$\ddot{x}(t) + \gamma \dot{x}(t) + \omega_0 x(t) + \alpha x^3(t) = F(t)$$

positive (negative) α could be seen as a
hardening (softening) of the spring
 constant

$$\ddot{x}(t) + \gamma \dot{x}(t) + x(t)(\omega_0 + \alpha x^2(t)) = F(t)$$

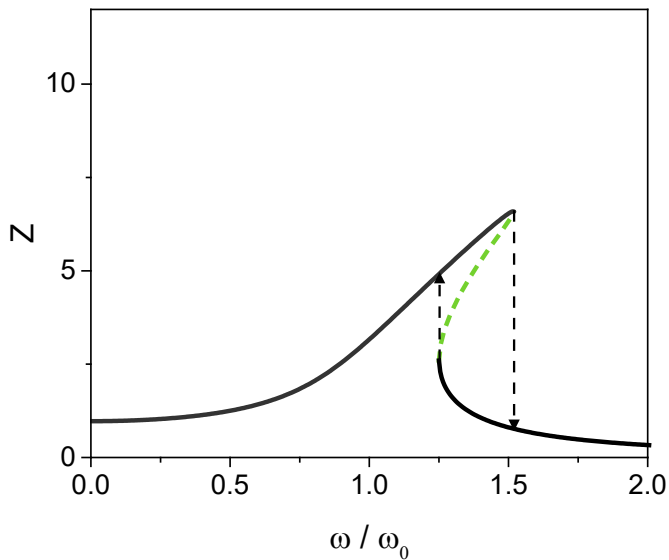
$$x(t) = Z \cos(\omega t - \psi)$$

Duffing Oscillator



Duffing Equation

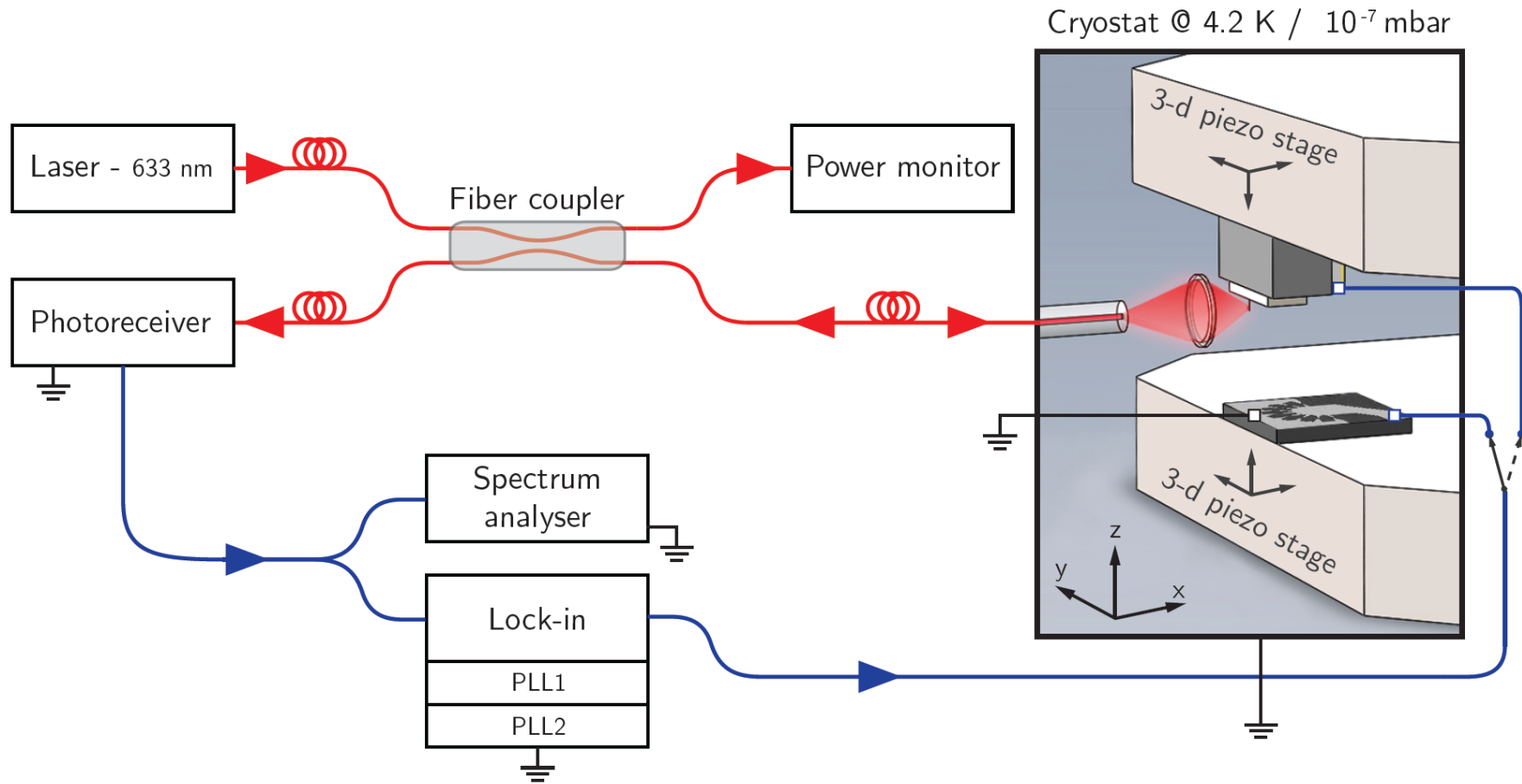
$$Z^2 \left(\omega^2 - \omega_0^2 - \frac{3}{4} \alpha Z^2 \right)^2 + (\gamma Z \omega)^2 = \hat{F}$$



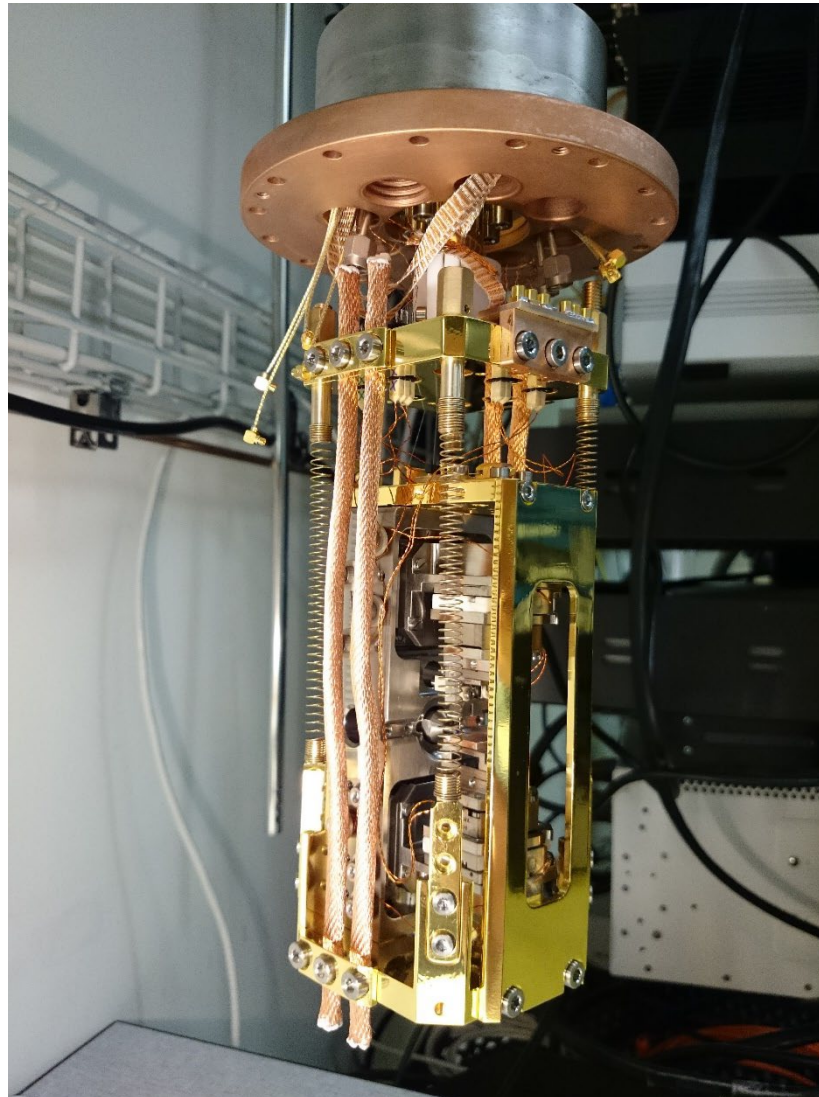
Bistable solution!

The jumping point depends on the history of the resonator

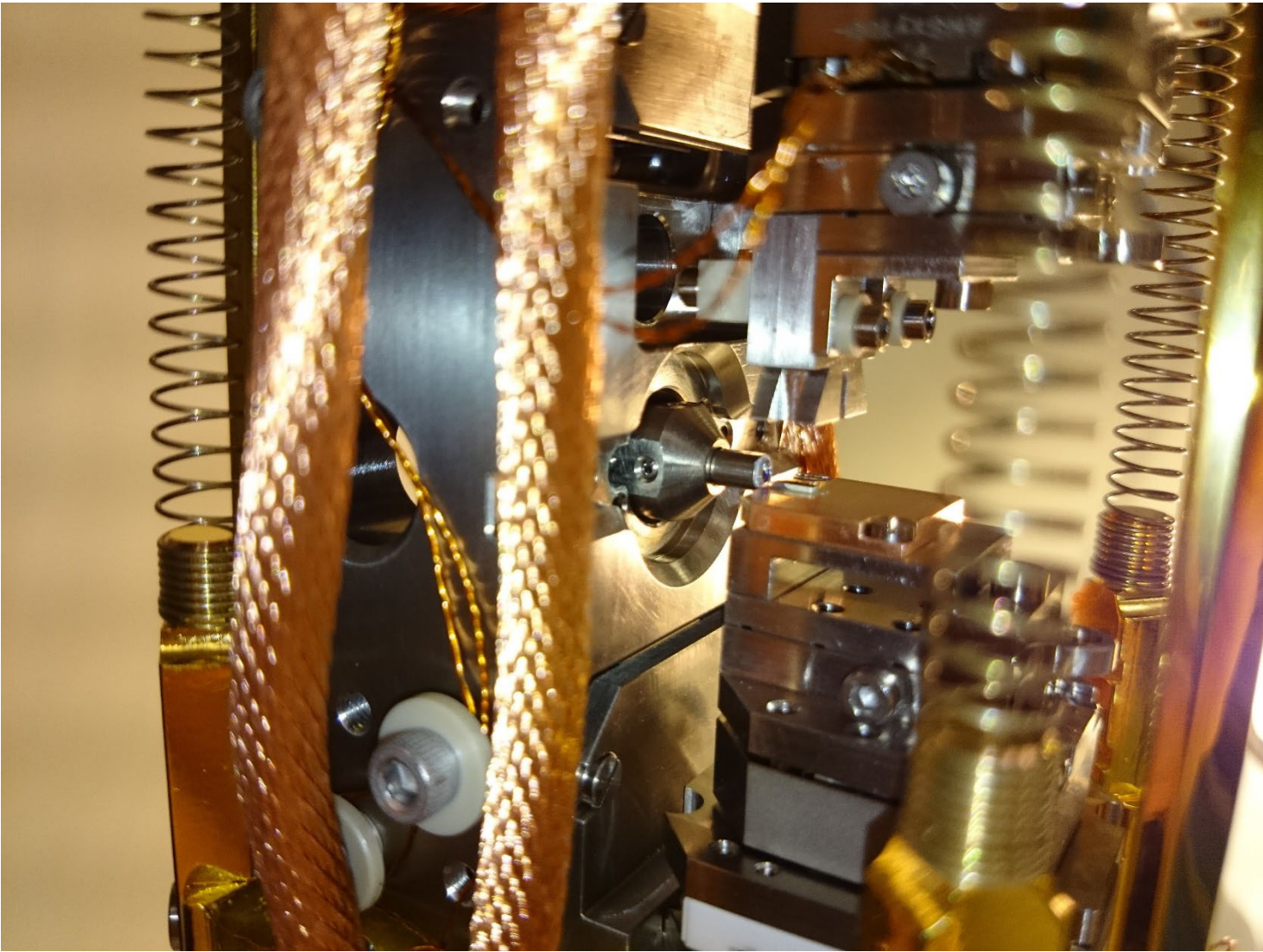
Low-temperature scanning NW setup



Low-temperature scanning NW setup

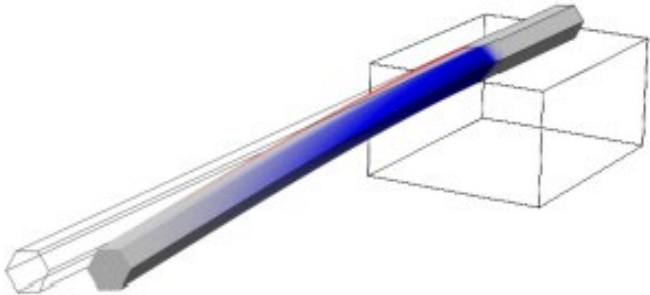


Low-temperature scanning NW setup

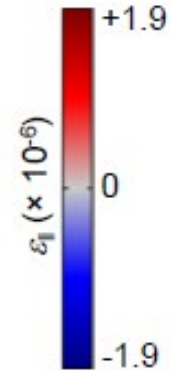
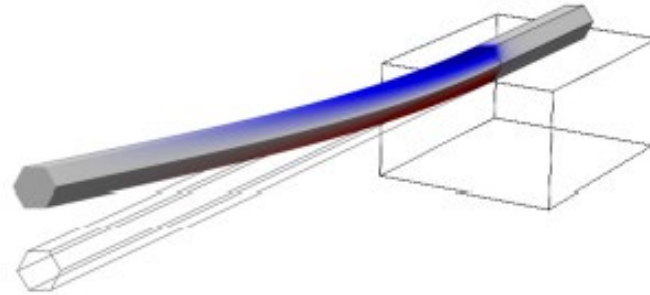


Mechanical modes

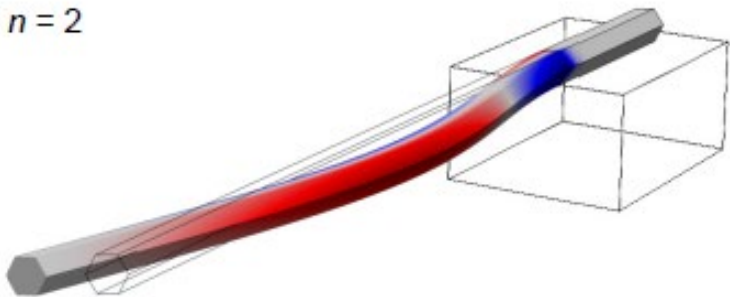
$n=0$



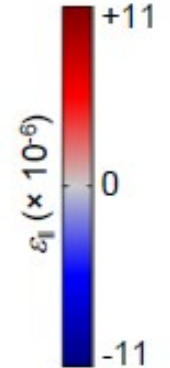
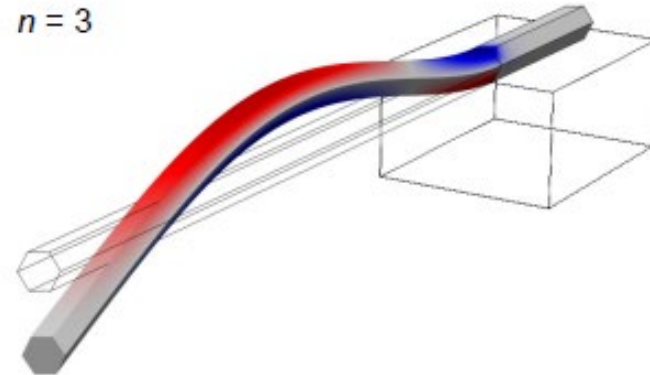
$n=1$



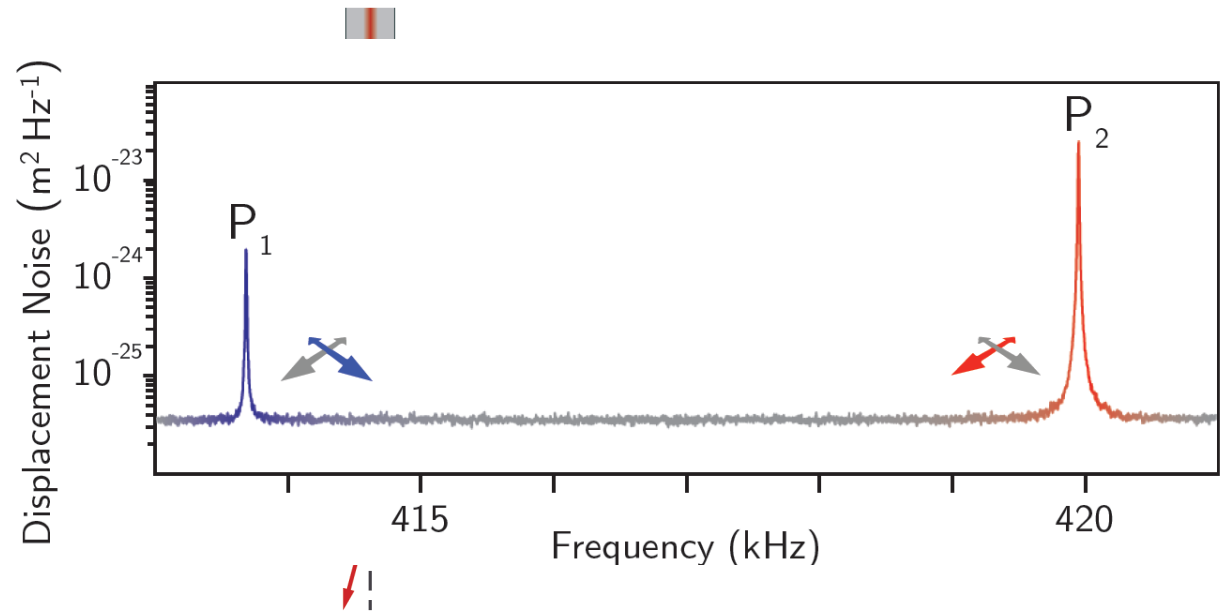
$n=2$



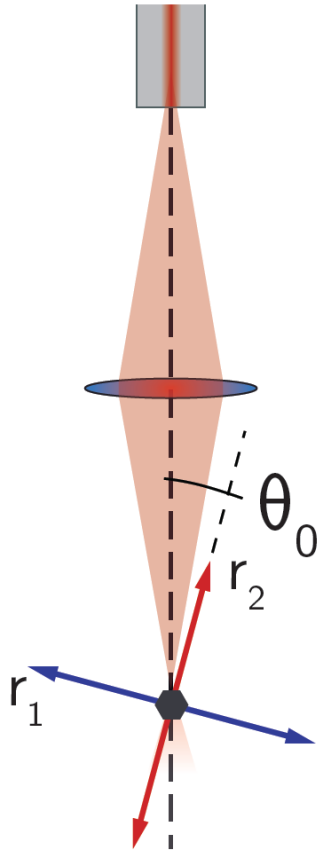
$n=3$



Nanowire mode doublet



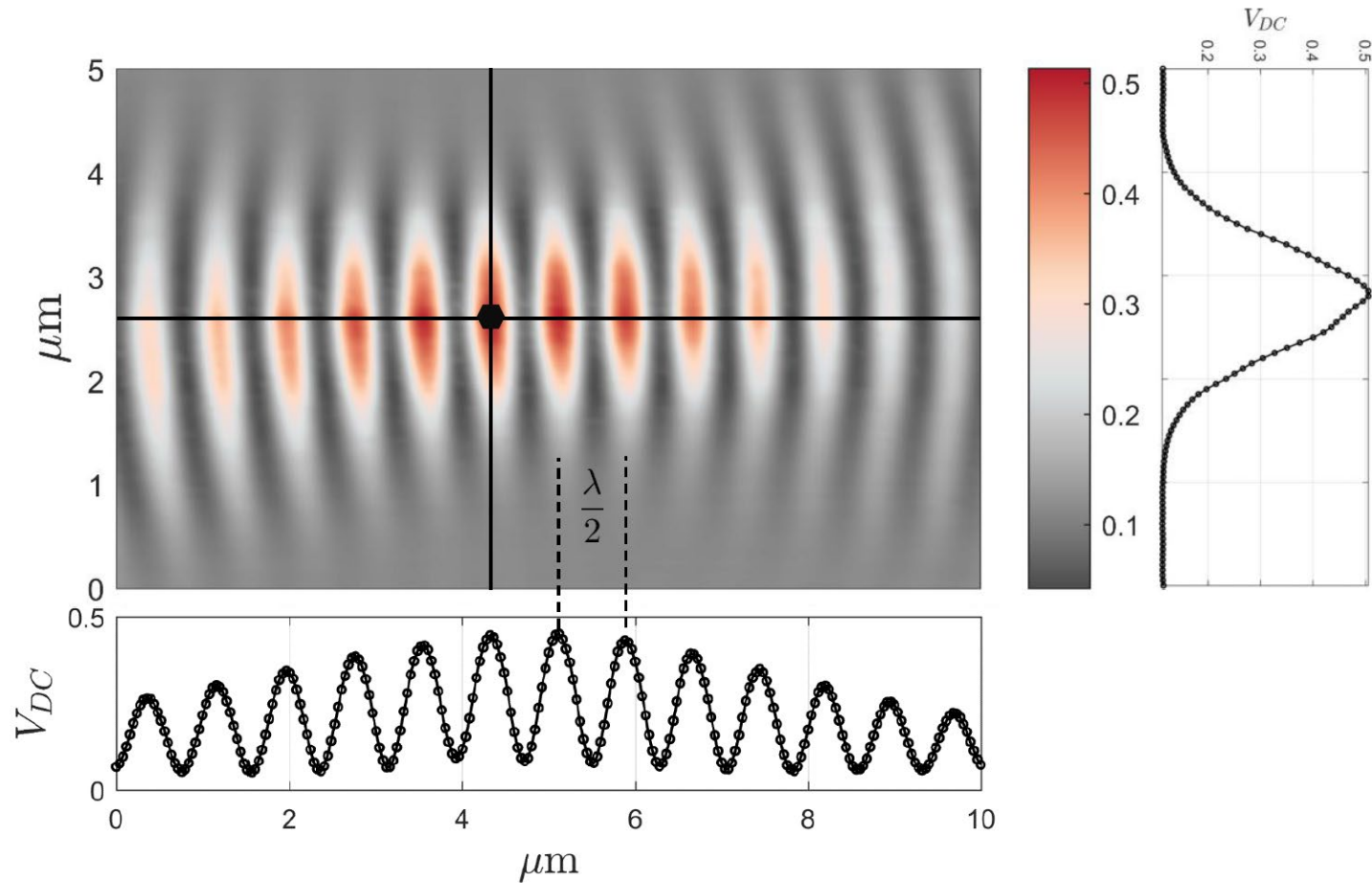
Interferometric detection



Oscillation direction estimation

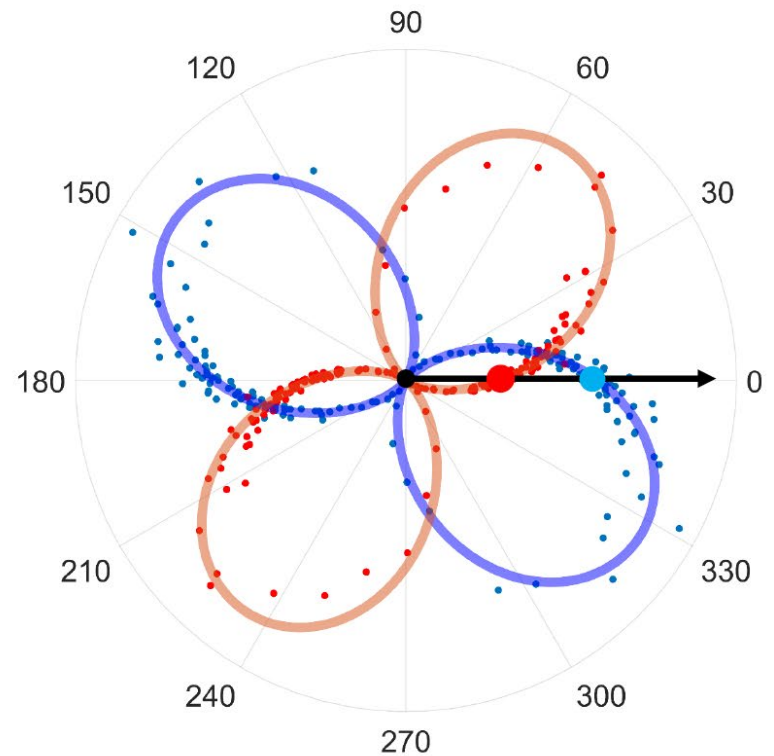
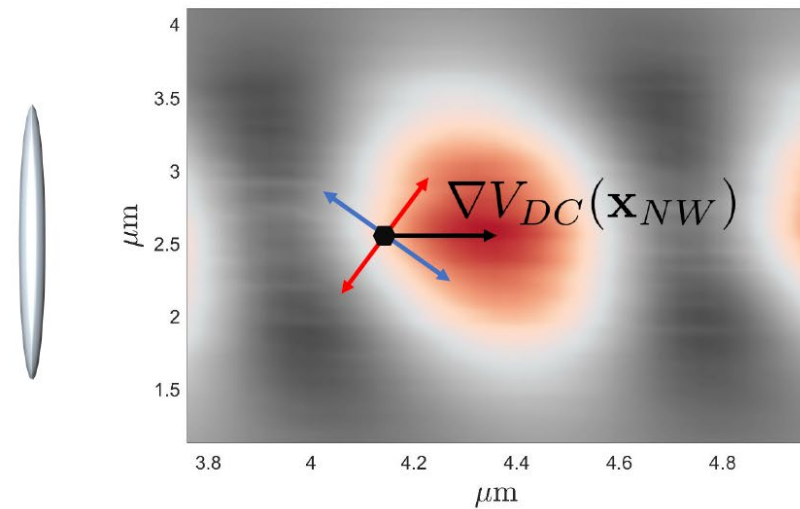
- Mean square displacement:
$$\langle x^2 \rangle = P_1 + P_2 = \langle r_1^2 \rangle \sin^2 \theta_0 + \langle r_2^2 \rangle \cos^2 \theta_0$$
- Angle: $\theta_0 = \arctan\left(\frac{f_1}{f_2} \sqrt{\frac{P_1}{P_2}}\right)$

Interferometric measurement of NW motion



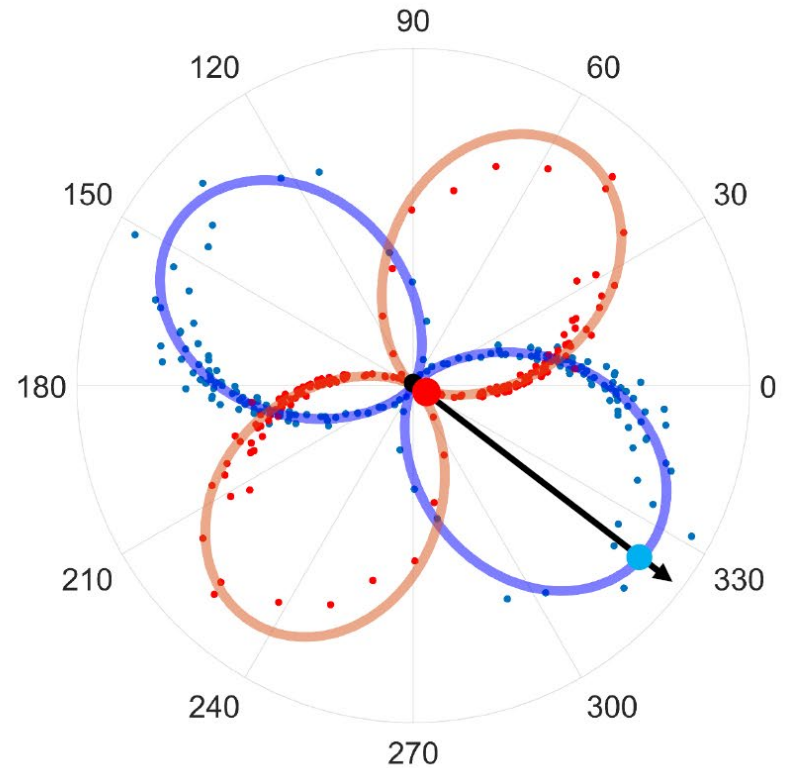
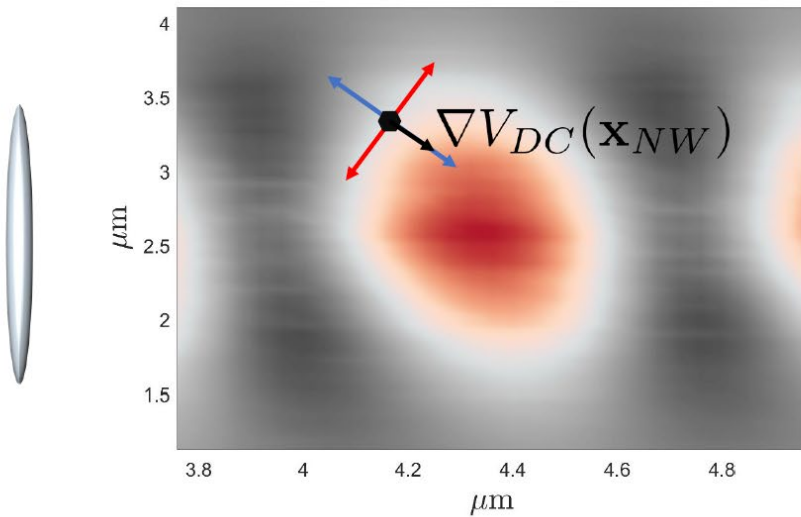
A. Gloppe et al. In: *Nat Nano* 9 (2014), pp. 920–926.

Interferometric measurement of NW motion



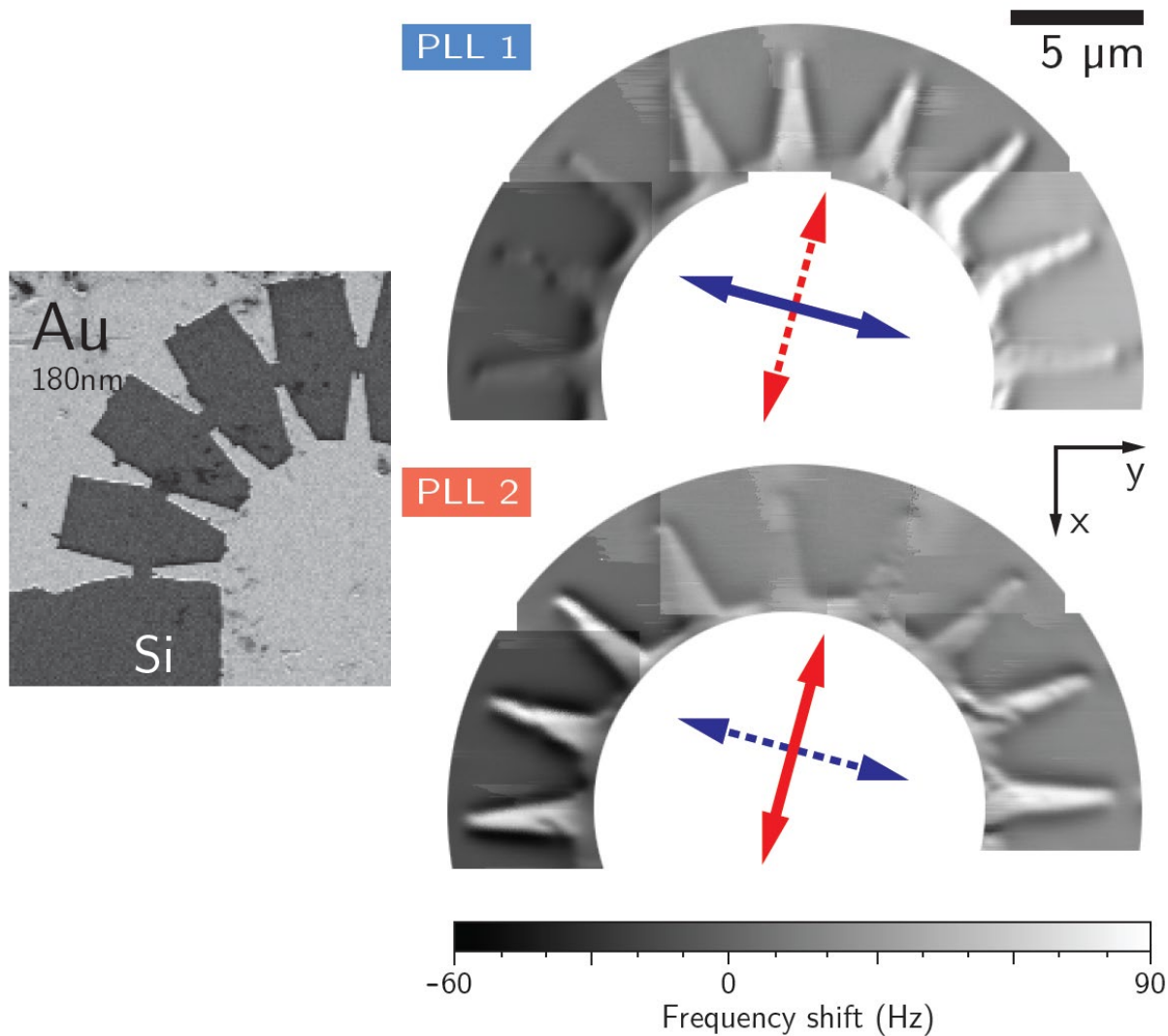
A. Gloppe et al. In: *Nat Nano* 9 (2014), pp. 920–926.

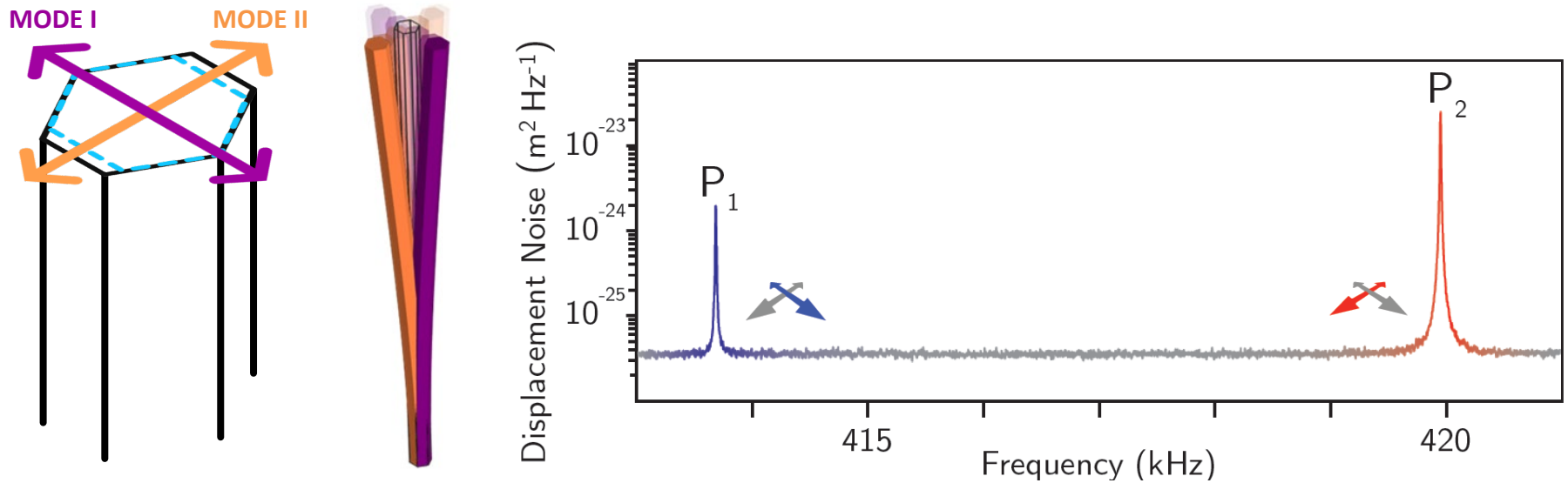
Interferometric measurement of NW motion



A. Gloppe et al. In: *Nat Nano* 9 (2014), pp. 920–926.

Two-mode lateral force microscopy





- Slightly asymmetric nanowire gives two non-degenerate flexural modes

$$\omega_0 = \beta_n \sqrt{\frac{5EA}{24m} \frac{d}{L^2}}$$

$$m\ddot{r}_i + \Gamma_i\dot{r}_i + k_i r_i = F_{th} + F_i$$

$$F_i \approx F_i(0) + r_j \left. \frac{\partial F_i}{\partial r_j} \right|_0$$

$$m\ddot{r}_i + \Gamma_i\dot{r}_i + k_i r_i = F_{th} + F_i(0) + F_{ij}r_j$$

$$m\ddot{\mathbf{r}} + \bar{\Gamma} \cdot \dot{\mathbf{r}} + \bar{K} \cdot \mathbf{r} = \mathbf{F}_{th} + \mathbf{F}_0,$$

$$\bar{\Gamma} \equiv \begin{pmatrix} \Gamma_1 & 0 \\ 0 & \Gamma_2 \end{pmatrix},$$

$$\bar{K} \equiv \begin{pmatrix} k_1 - F_{11} & -F_{21} \\ -F_{12} & k_2 - F_{22} \end{pmatrix}$$

$$k'_1 = \frac{1}{2} \left[k_1 + k_2 - F_{11} - F_{22} + \sqrt{(k_1 - k_2 - F_{11} + F_{22})^2 + 4F_{12}F_{21}} \right]$$

$$\hat{\mathbf{r}}'_1 = \frac{1}{\sqrt{(k_2 - F_{22} - k'_1)^2 + F_{12}^2}} \begin{pmatrix} k_2 - F_{22} - k'_1 \\ F_{12} \end{pmatrix};$$

$$k'_2 = \frac{1}{2} \left[k_1 + k_2 - F_{11} - F_{22} - \sqrt{(k_1 - k_2 - F_{11} + F_{22})^2 + 4F_{12}F_{21}} \right]$$

$$\hat{\mathbf{r}}'_2 = \frac{1}{\sqrt{(k_1 - F_{11} - k'_2)^2 + F_{21}^2}} \begin{pmatrix} F_{21} \\ k_1 - F_{11} - k'_2 \end{pmatrix}.$$

$$k'_1 \approx k_1 - F_{11},$$

$$\hat{\mathbf{r}}'_1 \approx \frac{1}{\sqrt{(k_1 - k_2)^2 + F_{12}^2}} \begin{pmatrix} k_1 - k_2 \\ -F_{12} \end{pmatrix}$$

$$k'_2 \approx k_2 - F_{22},$$

$$\hat{\mathbf{r}}'_2 \approx \frac{1}{\sqrt{(k_1 - k_2)^2 + F_{21}^2}} \begin{pmatrix} F_{21} \\ k_1 - k_2 \end{pmatrix}$$

$$\Delta f_i = f'_i - f_i \approx -\frac{f_i}{2k_i} F_{ii}$$

$$\frac{\partial F_i}{\partial r_i} \approx -2k_i \left(\frac{\Delta f_i}{f_i} \right)$$

$$\tan \phi_i \approx \frac{F_{ij}}{|k_i - k_j|}$$

$$\frac{\partial F_i}{\partial F_j} \approx |k_i - k_j| \tan \phi_i$$

In-plane spatial force derivatives

- NW tip equations of motion:

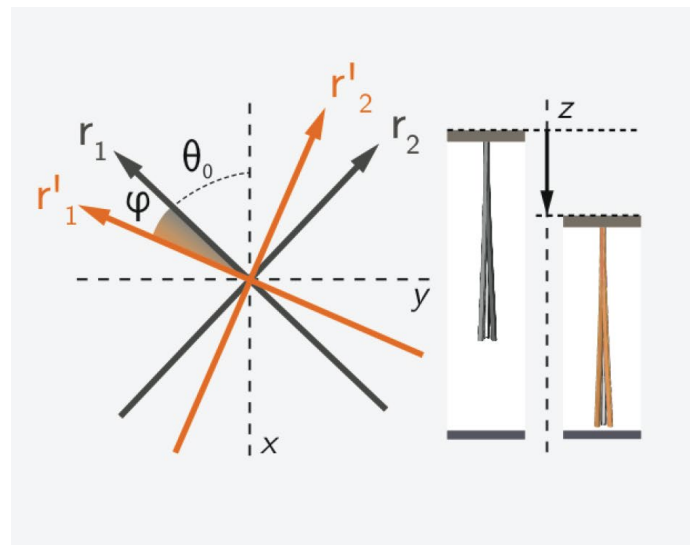
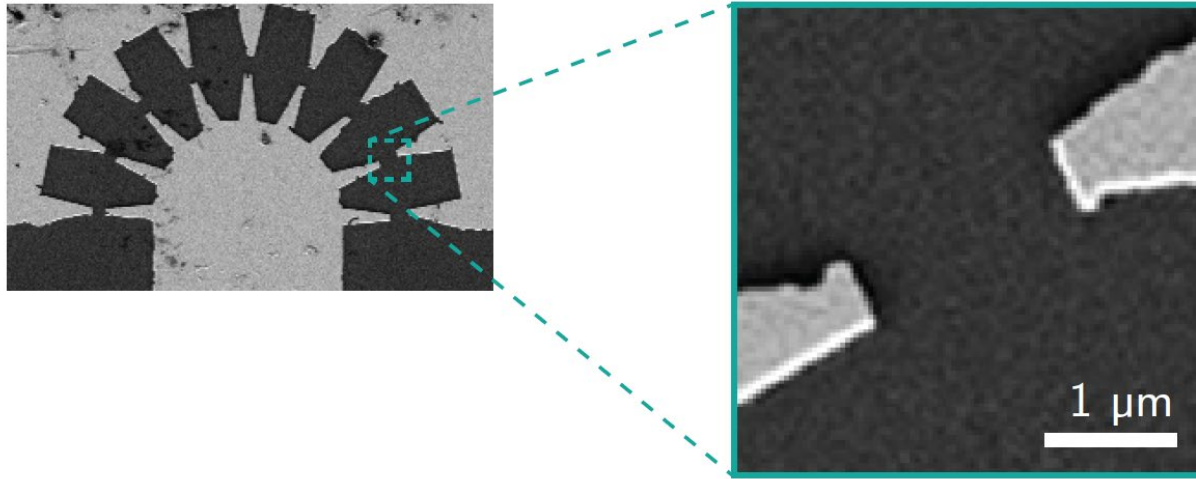
$$m\ddot{r}_i + \Gamma_i\dot{r}_i + k_i r_i = F_{th} + F_i$$

- For small oscillations and $\frac{\partial F}{\partial r} \ll k_{1,2}$:

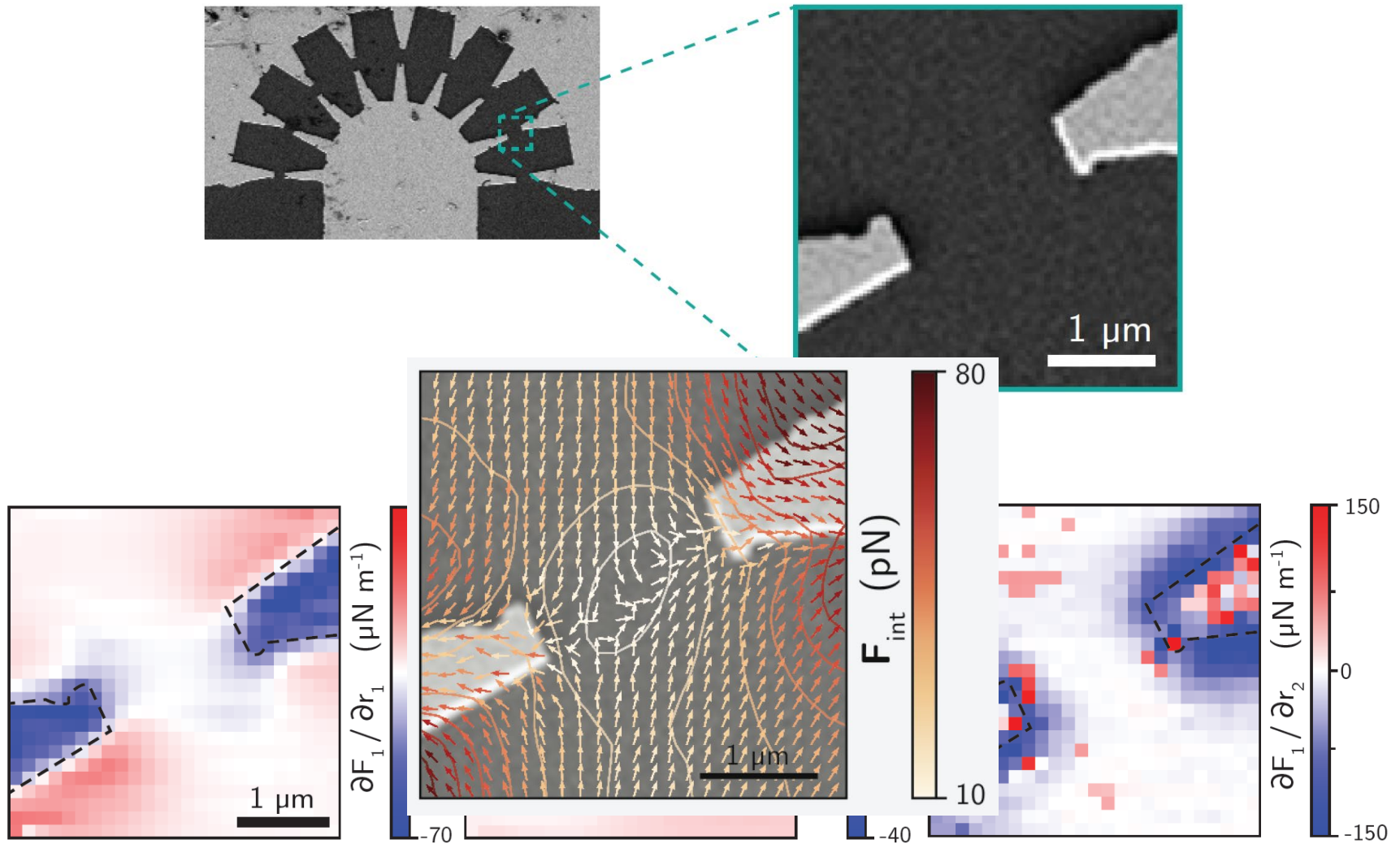
$$\frac{\partial F_i}{\partial r_i} \approx -2k_i \frac{\Delta f_i}{f_i}$$

$$\frac{\partial F_i}{\partial r_j} \approx |k_i - k_j| \tan \phi$$

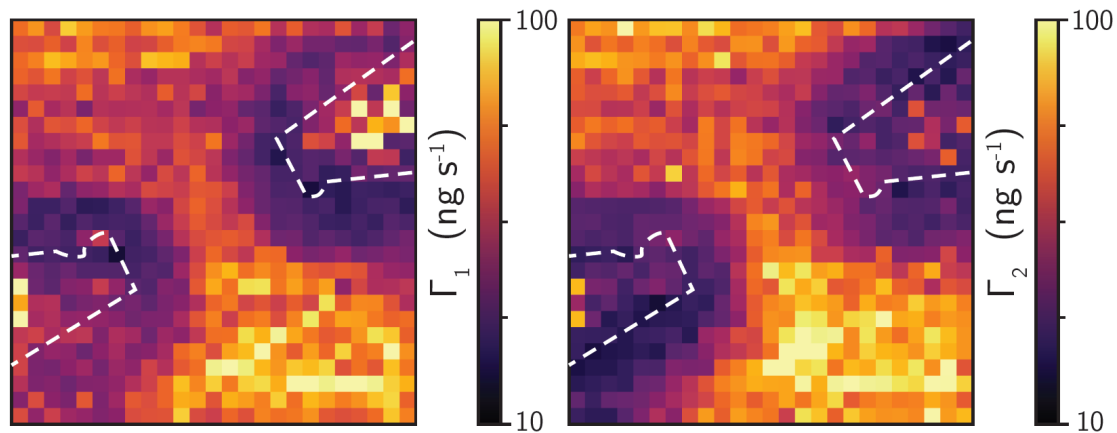
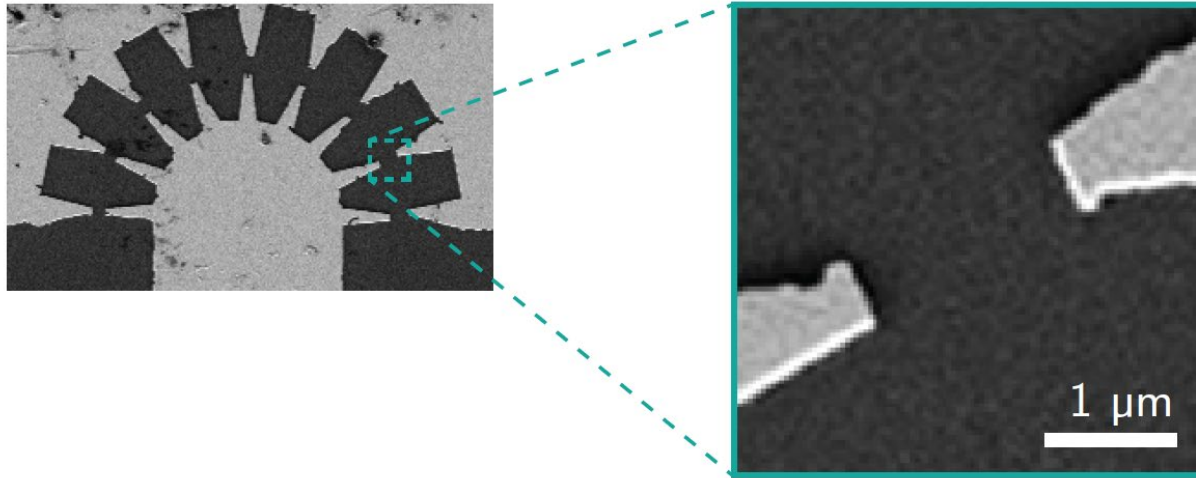
NW scanning force microscopy



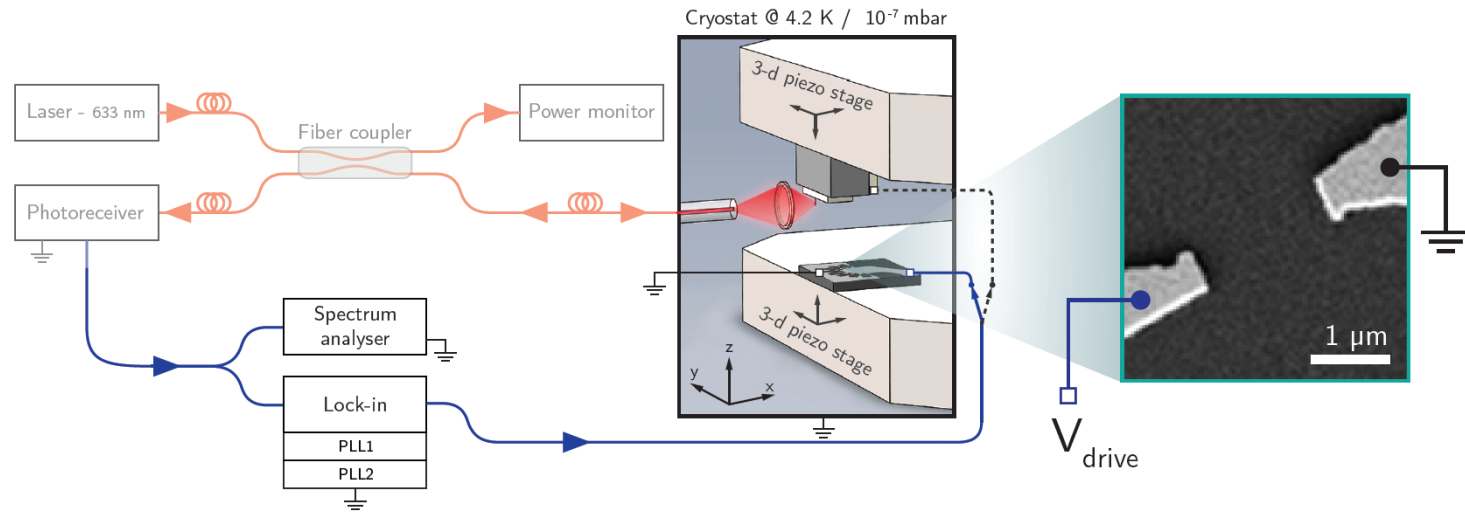
NW scanning force microscopy



NW scanning force microscopy: Friction



Driving with AC voltage



Electrostatic tip-sample forces

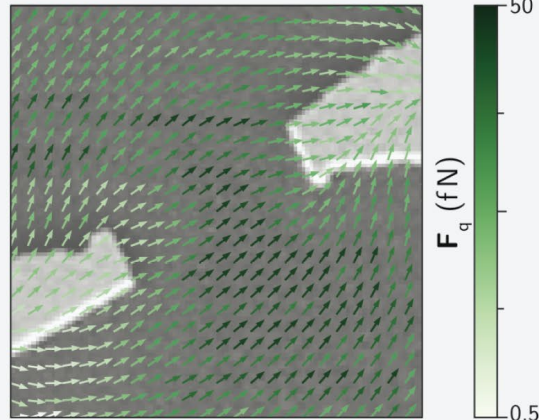
- Charge $\mathbf{F}_q = q\mathbf{E}$ $V_{drive} = V_q \sin(\omega_0 t)$ $V_q = 2mV$
- Polarizability $\mathbf{F}_p = -\nabla(\alpha|\mathbf{E}|^2)$ $V_{drive} = V_p \sin(\frac{\omega_0}{2} t)$ $V_p = 20mV$

AC force fields

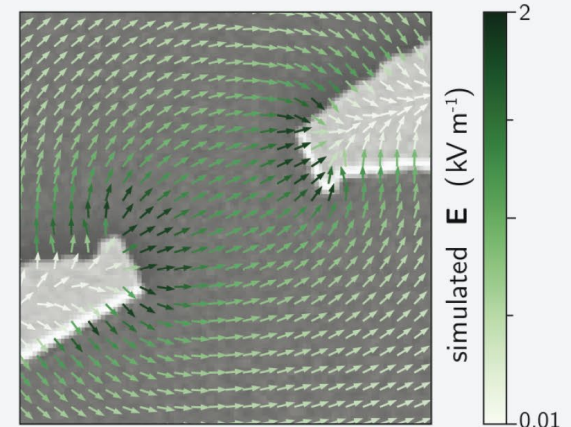
Electrostatic force

- $\mathbf{F}_q = q\mathbf{E}$
- V_{drive} sweep through $f_{1,2}$
- $q_{tot} = 30 \pm 10e$

Experiment

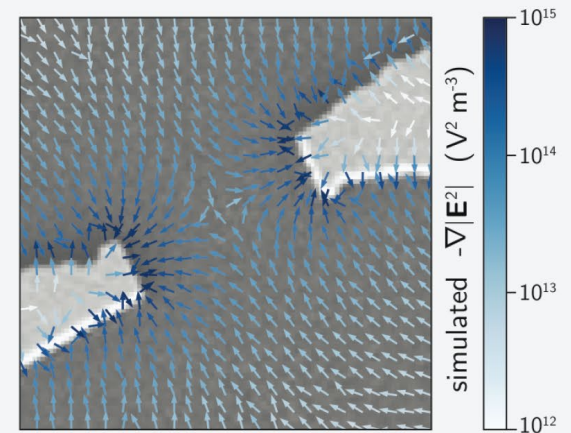
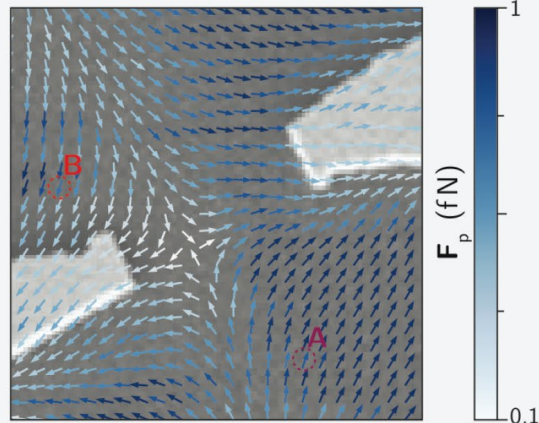


Simulation



Dielectric force

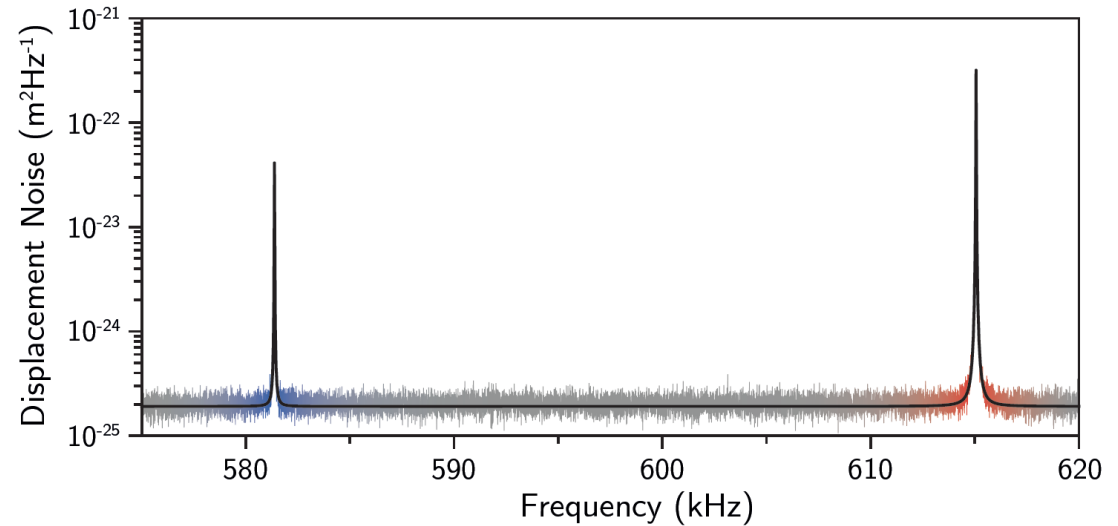
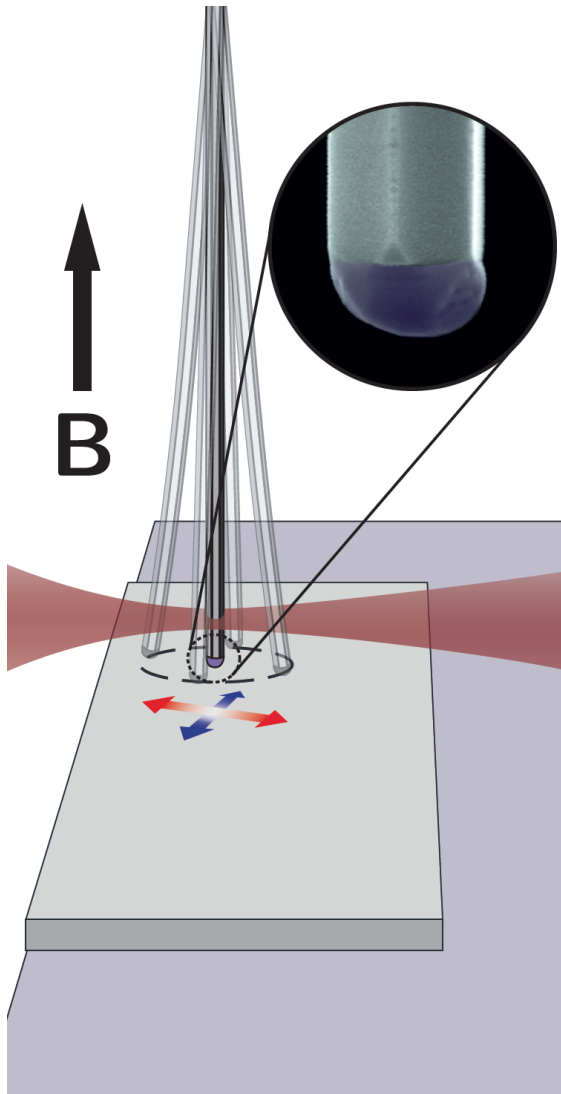
- $\mathbf{F}_p = -\nabla(\alpha|\mathbf{E}|^2)$
- V_{drive} sweep through $\frac{f_{1,2}}{2}$
- $\alpha = 10^{-29} \frac{C}{Vm}$



N. Rossi et al., *Nat. Nanotechnol.* **12**, 150 (2017).

See also: Mercier de Lépinay et al., *Nat. Nanotechnol.* **12**, 156 (2017).

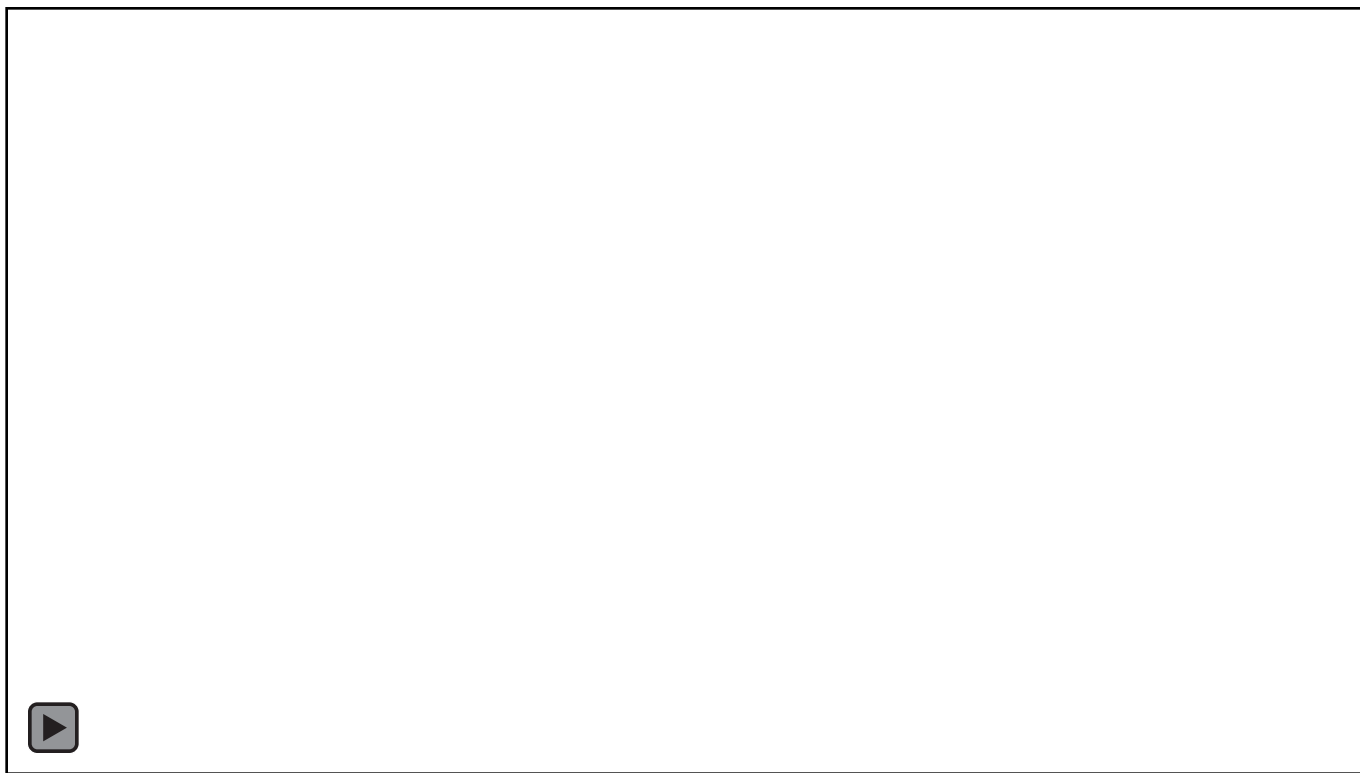
NWs with magnetic tips



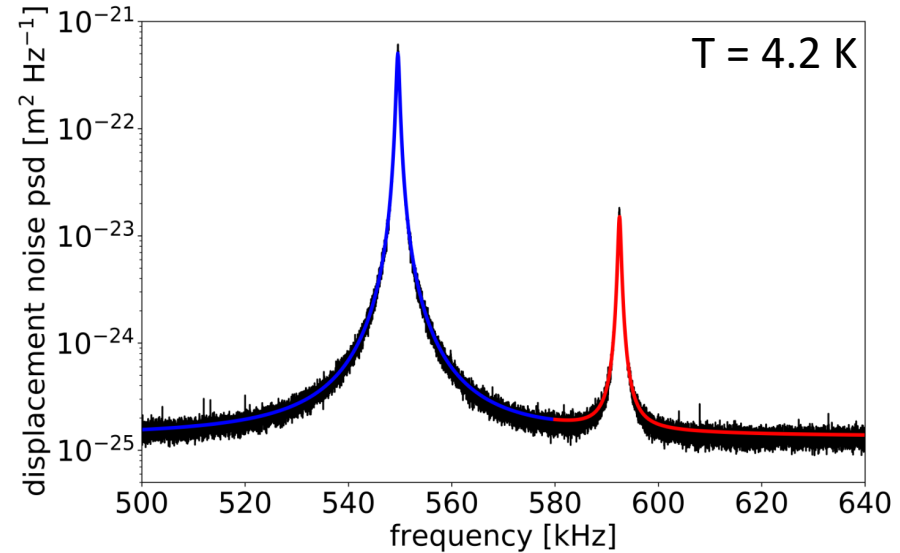
Length $\sim 17 \pm 1 \mu\text{m}$ with diameter $\sim 225 \pm 15 \text{ nm}$

- $f \sim [500 - 700] \text{ kHz}$
- $Q \sim [30 - 50] \times 10^3$
- $k \sim [1 - 10] \text{ mN/m}$
- $M \sim 700 \text{ fg}$
- $\Gamma \sim 50 \times 10^{-15} \text{ kg/s}$
- $F_{min} \sim 4 \text{ aN}/\sqrt{\text{Hz}}$

Fully magnetic NWs

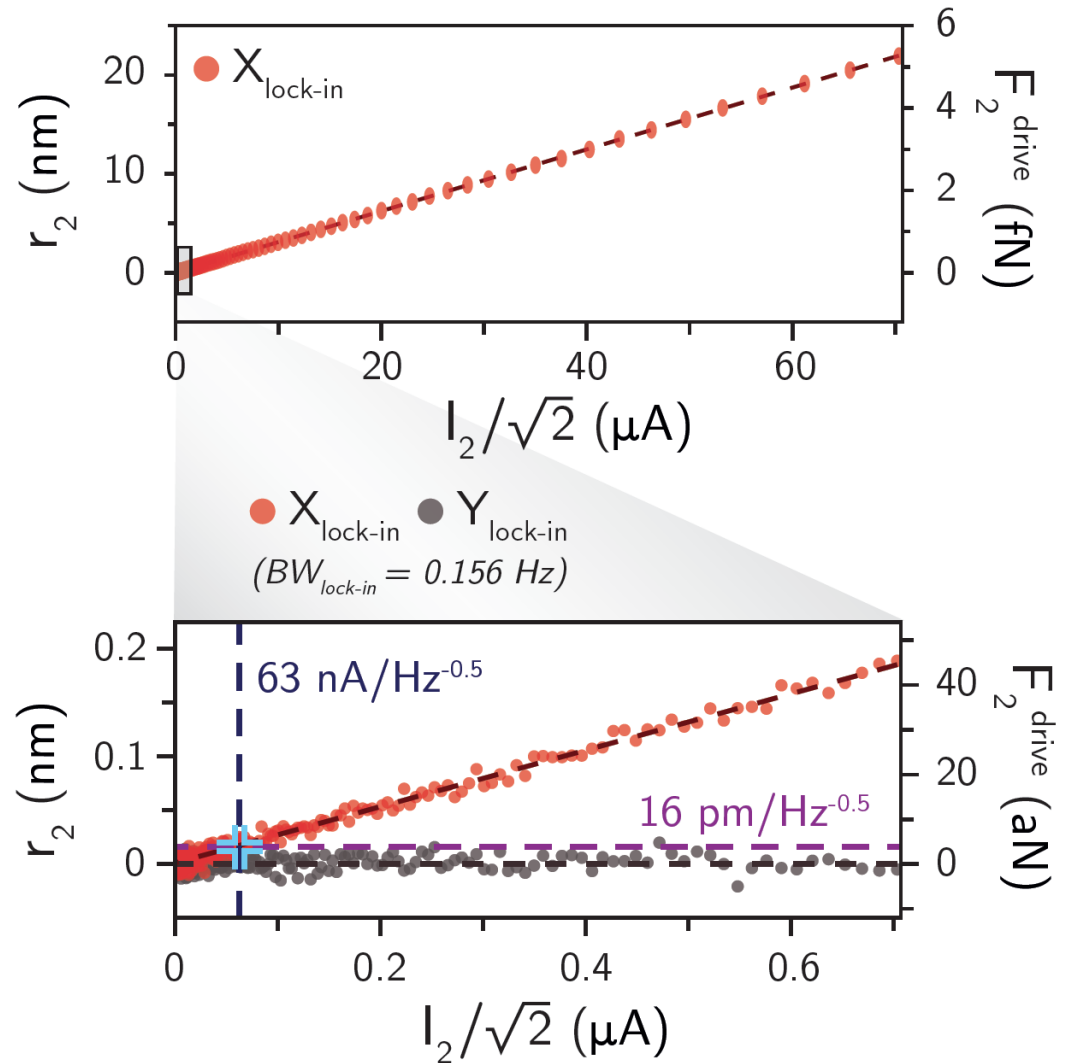
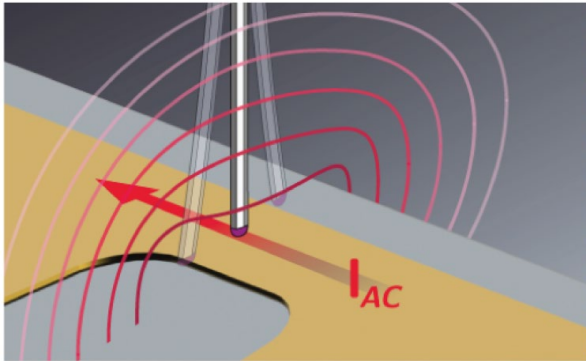


Fully magnetic NWs



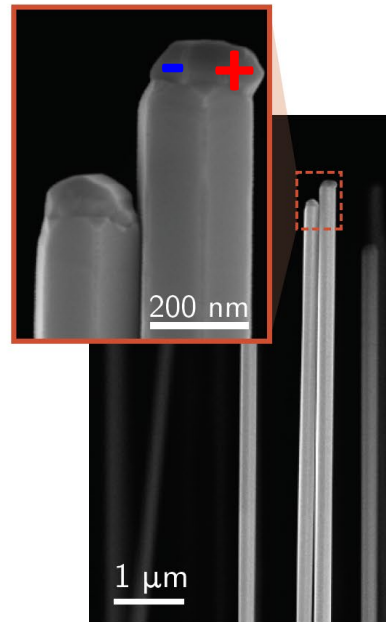
- 10 μm length, 100 nm diameter
- $Q \approx 2000$
- $k \approx 1$ mN/m
- $m_{\text{eff}} \approx 200$ fg
- $F_{\text{min}} \approx 25$ aN/Hz^{1/2}

Quantifying sensitivity



Quantifying sensitivity

MBE-grown MnAs-tipped NWs



$$F_{\min} = 4 \text{ aN}/(\text{Hz})^{1/2}$$

At 250 nm spacing:

$$dB/dx_{\min} = 11 \text{ mT}/\text{m}(\text{Hz})^{1/2}$$

FEBID-grown Co NWs



$$F_{\min} = 25 \text{ aN}/(\text{Hz})^{1/2}$$

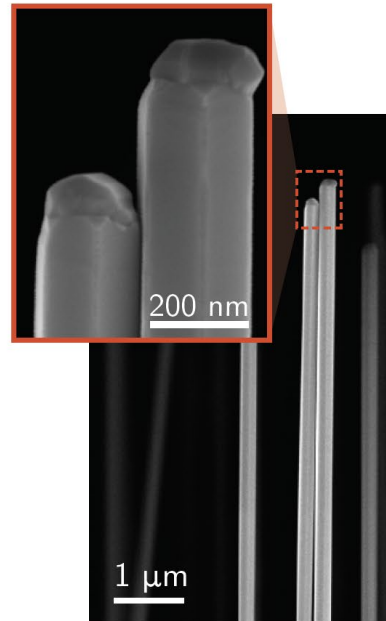
At 200 nm spacing:

$$B_{\min} = 3 \text{ nT}/(\text{Hz})^{1/2}$$

Rossi et al., *Nano Lett.* **19**, 930 (2019).
Mattiat et al., *Phys. Rev. Appl.* **13**, 044043 (2020).

Quantifying sensitivity

MBE-grown MnAs-tipped NWs



250 nm tip diameter

At 250 nm spacing:

$$M_{\min} = 50 \mu_B / (\text{Hz})^{1/2}$$

$$\Phi_{\min} = 1 \mu\Phi_0 / (\text{Hz})^{1/2}$$

$$I_{\min} = 10 \text{ nA} / (\text{Hz})^{1/2}$$

FEBID-grown Co NWs



100 nm tip diameter

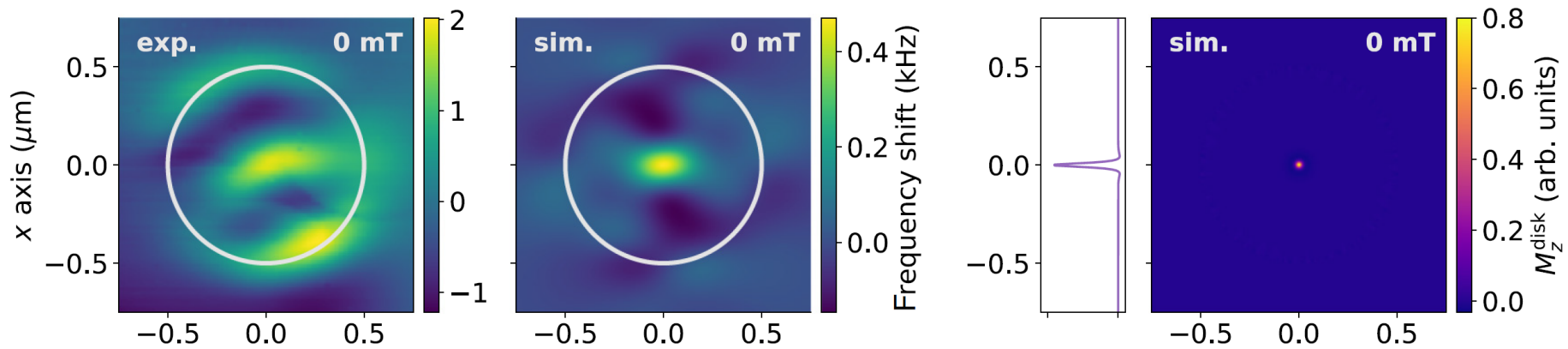
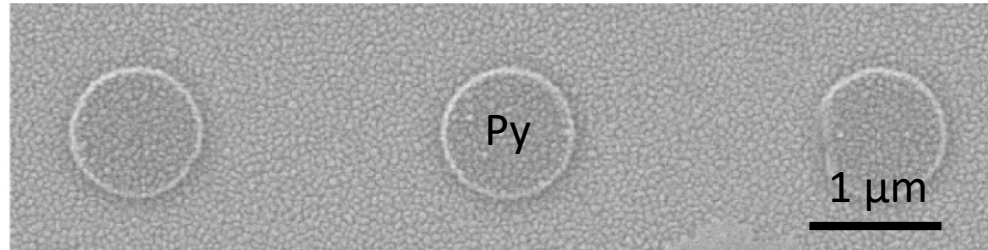
At 100 nm spacing:

$$M_{\min} = 60 \mu_B / (\text{Hz})^{1/2}$$

$$\Phi_{\min} = 6 \mu\Phi_0 / (\text{Hz})^{1/2}$$

$$I_{\min} = 8 \text{ nA} / (\text{Hz})^{1/2}$$

NW MFM

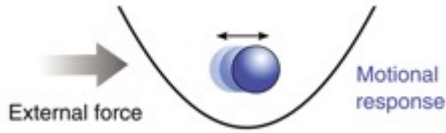


CONTROL OF LEVITATED NANOPARTICLES

The image shows a dark, industrial-looking optical setup. On the left, a large, multi-faceted black component, possibly a lens or part of a microscope, is visible. A bright, horizontal light beam passes through it. On the right, another large black component, possibly a lens or part of a microscope, is visible. A bright, horizontal light beam passes through it. A small, bright green spot is visible in the center, between the two components, likely representing a levitated nanoparticle. The background is dark and out of focus.

MOTIVATION

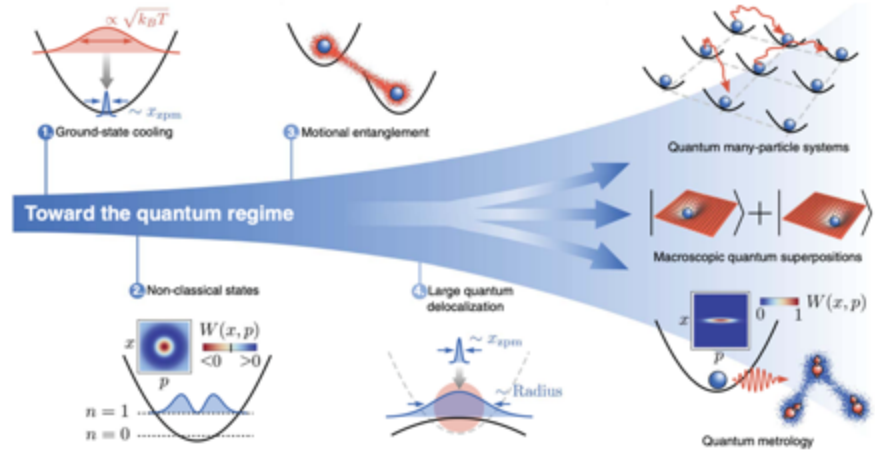
Sensing



$$F_{\min} = \sqrt{\frac{4k_B T m \gamma_j}{t_m}}$$

Force	Signal form	Measurement
Constant	<p>Signal</p> <p>Time t</p>	<p>1) 2) 3)</p> <p>Probability distribution</p> <p>Position</p>
Impulse	<p>Signal</p> <p>Time t</p>	<p>1) 2)</p> <p>Motional energy</p> <p>Time t</p>
Oscillating	<p>Signal</p> <p>Time t</p>	<p>Motional power spectral density</p> <p>Power spectral density</p> <p>Frequency</p>

Fundamental physics



ACKNOWLEDGMENTS

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Mattana



Massimiliano
Rossi



Louisiane
Devaud



Eric
Bonvin

HU:



Felix
Tebbenjohanns

IAV:



Jan
Gieseler

SNB:



Dominik
Windey

ETH:



Romain
Quidant

IQQI:



Oriol
Romero-Isart

U.Vienna: U.Innsbruck:



Markus
Aspelmeyer

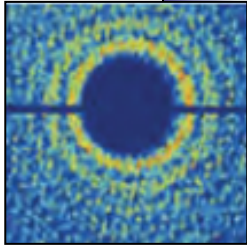


Tracy
Northup

OUTLINE

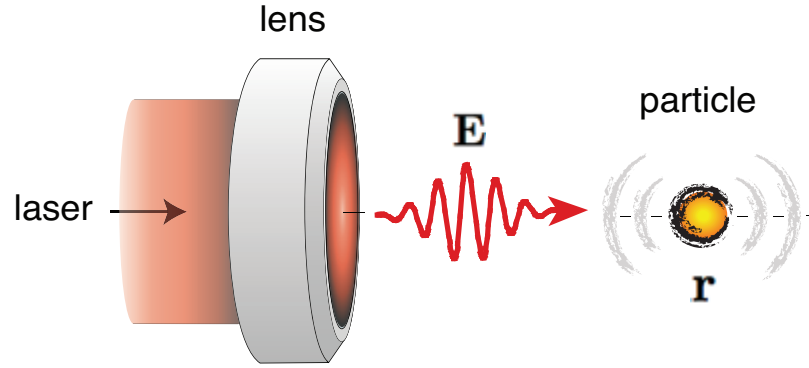
- 1: INTRODUCTION (A PERSONAL STORY)
- 2: Q-XTREME & GROUND-STATE
- 3: STATE EXPANSION
- 4: OUTLOOK

LINAC Coherent Light Source (LCLS)



www.slac.stanford.edu

CONTROL BY OPTICAL FORCES



$$m\ddot{\mathbf{r}} = \langle \mathbf{F} \rangle$$

$$\frac{\alpha'}{2} \sum_{i=x,y,z} \text{Re} \{ \mathbf{E}_i^* \nabla \mathbf{E}_i \} + \frac{\alpha''}{2} \sum_{i=x,y,z} \text{Im} \{ \mathbf{E}_i^* \nabla \mathbf{E}_i \}$$

$$\nabla [\mathbf{E}^* \cdot \mathbf{E}]$$

letters to nature

Cavity cooling of a microlever

Constanze Hühberger Metzger & Khaled Karrai

*Center for NanoScience and Sektion Physik, Ludwig-Maximilians-Universität,
Geschwister-Scholl-Platz 1, 80539 München, Germany*

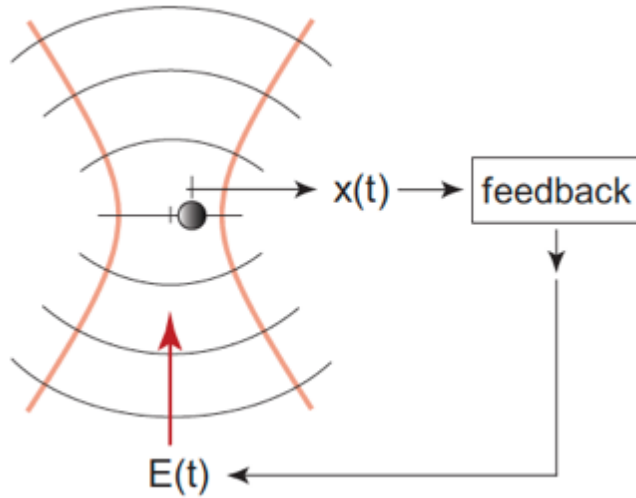
1002 NATURE | VOL 432 | 23/30 DECEMBER 2004 | www.nature.com/nature

$$m \frac{d^2 z}{dt^2} + m\Gamma \frac{dz}{dt} + Kz = F_{\text{th}} + \sum_n \int_0^t \frac{dF_n[z(t')]}{dt} h_n(t - t') dt'$$

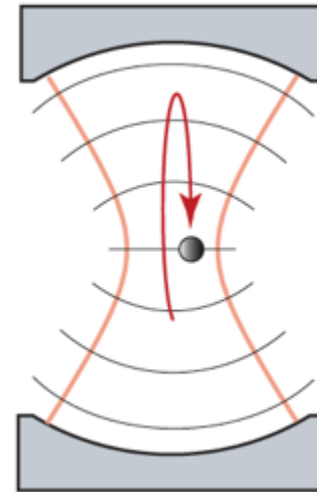
As we will see below, the essence of cooling is based on the fact that the optically induced forces acting on the lever are delayed with respect to a sudden change in the lever position.

FEEDBACK CONTROL

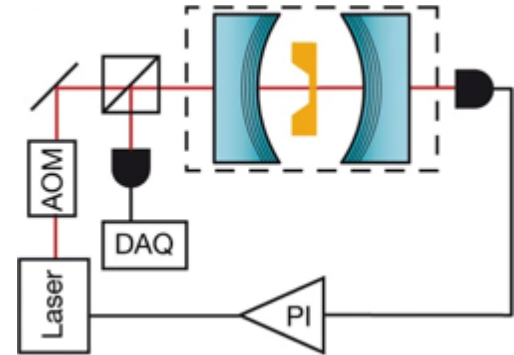
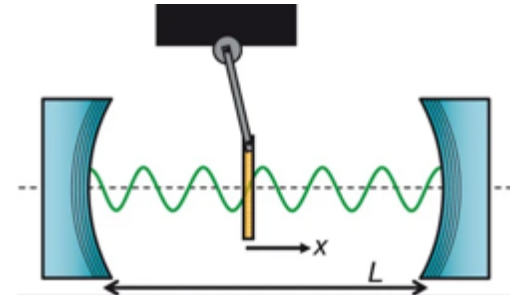
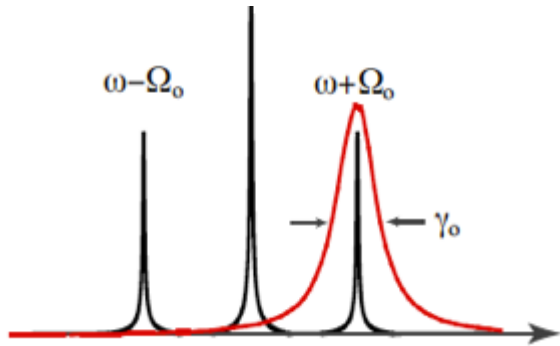
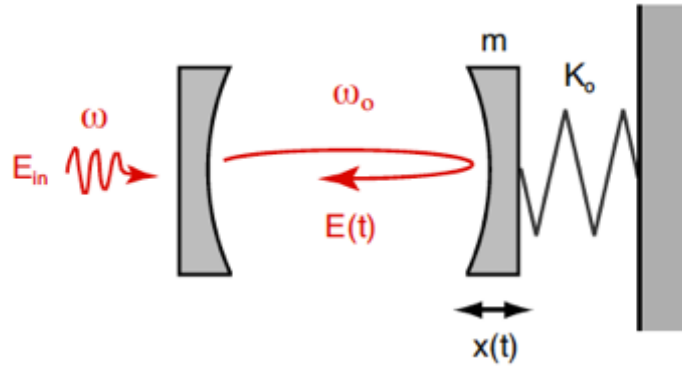
Active Feedback:



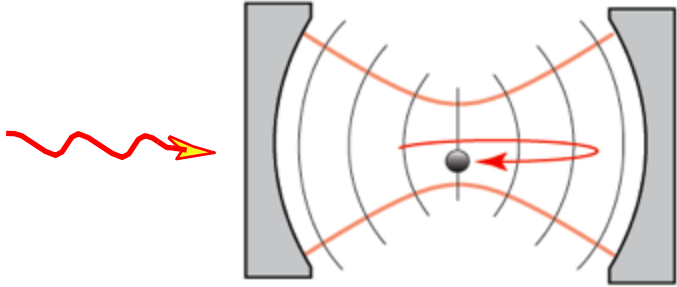
Passive Feedback:



CAVITY OPTOMECHANICS



LEVITATED CAVITY OPTOMECHANICS



Cavity opto-mechanics using an optically levitated nanosphere

D. E. Chang^a, C. A. Regal^b, S. B. Papp^b, D. J. Wilson^b, J. Ye^{b,c}, O. Painter^d, H. J. Kimble^{b,1}, and P. Zoller^{b,e}

PNAS | January 19, 2010 | vol. 107 | no. 3 | 1005–1010

New Journal of Physics

The open-access journal for physics

Toward quantum superposition of living organisms

Oriol Romero-Isart^{1,4}, Mathieu L Juan², Romain Quidant^{2,3} and J Ignacio Cirac¹

New Journal of Physics 12 (2010) 033015

PHYSICAL REVIEW A 81, 023826 (2010)

Cavity cooling of an optically trapped nanoparticle

P. F. Barker

Department of Physics and Astronomy, University College London, WC1E 6BT, United Kingdom

M. N. Shneider

Applied Physics Group, Department of Mechanical and Aerospace Engineering, Princeton University, Princeton, New Jersey 08544, USA

Cavity cooling of an optically levitated submicron particle

Nikolai Kiesel^{1,2}, Florian Blaser¹, Uroš Delić, David Grass, Rainer Kaltenbaek, and Markus Aspelmeyer²

Vienna Center for Quantum Science and Technology (VCQ), Faculty of Physics, University of Vienna, A-1090 Vienna, Austria

14180–14185 | PNAS | August 27, 2013 | vol. 110 | no. 35

The damping γ_0 of the mechanical resonator is dominated by the ambient pressure of the background gas down to a few millibars (Fig. 2B). Below these pressures, the submicron particle is not stably trapped anymore, whereas trapping times up to several hours can be achieved at a pressure of a few millibars. This is a known, yet unexplained phenomenon (17, 18, 44).

Optical levitation in high vacuum

A. Ashkin and J. M. Dziedzic

Bell Telephone Laboratories, Holmdel, New Jersey 07733
(Received 17 November 1975)

Optical levitation of highly transparent particles has been observed in the high-vacuum regime where viscous damping and thermal conductivity are small, the particle is cooled only by thermal radiation, and radiometric forces are negligible. The effects of an impulse and adiabatic manipulation on the dynamics of a sphere were studied from atmospheric pressure down to $\sim 10^{-6}$ Torr. The calculated time for an oscillating particle to decay to half-amplitude due to the intrinsic optical damping at zero pressure is ~ 0.7 years.



Feedback stabilization of optically levitated particles

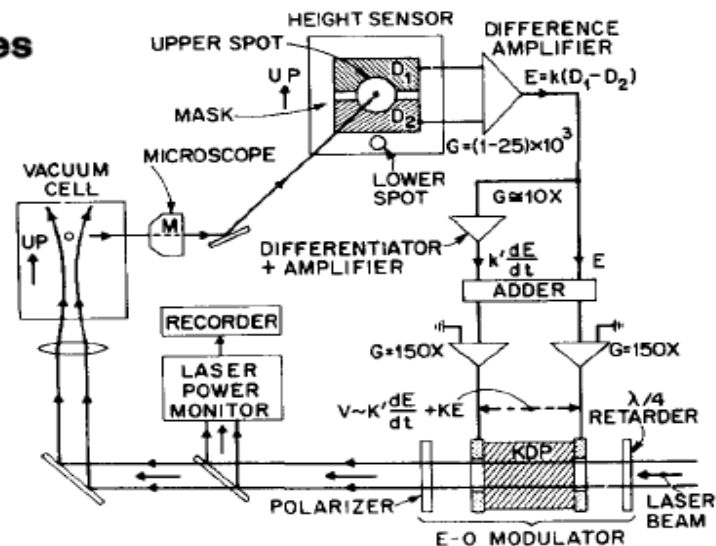
A. Ashkin and J. M. Dziedzic

Bell Telephone Laboratories, Holmdel, New Jersey 07733
(Received 5 November 1976)

We demonstrate the locking of an optically levitated sphere to an external reference using an electronic feedback system. This provides a new external source of damping for the stabilization and manipulation of particles in vacuum and at atmospheric pressure. The method permits accurate and continuous monitoring of applied forces. Numerous applications are suggested.

It is of interest to consider the intrinsic damping of an oscillating levitated particle in the limit of total vacuum, i.e., zero viscous damping. Consider first a

Particles $\sim 10\mu\text{m}$ in size



Cooling of a Mirror by Radiation Pressure

P. F. Cohadon,* A. Heidmann,[†] and M. Pinar[‡]

Laboratoire Kastler Brossel,[§] Case 74, 4 place Jussieu, F75252 Paris Cedex 05, France

(Received 30 March 1999; revised manuscript received 24 June 1999)

PRL 99, 017201 (2007)

PHYSICAL REVIEW LETTERS

week ending
6 JULY 2007

Feedback Cooling of a Cantilever's Fundamental Mode below 5 mK

M. Poggio,^{1,2} C. L. Degen,¹ H. J. Mamin,¹ and D. Rugar¹

¹*IBM Research Division, Almaden Research Center, 650 Harry Rd., San Jose California 95120, USA*

²*Center for Probing the Nanoscale, Stanford University, 476 Lomita Hall, Stanford California 94305, USA*

(Received 7 February 2007; published 2 July 2007)

nature
physics

LETTERS

PUBLISHED ONLINE: 20 MARCH 2010 | DOI: 10.1038/NPHYS2952

Millikelvin cooling of an optically trapped microsphere in vacuum

Tongcang Li, Simon Kheifets and Mark G. Raizen*

PRL 105, 173003 (2010)

PHYSICAL REVIEW LETTERS

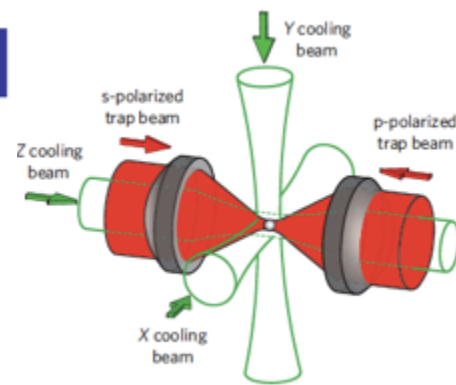
week ending
22 OCTOBER 2010



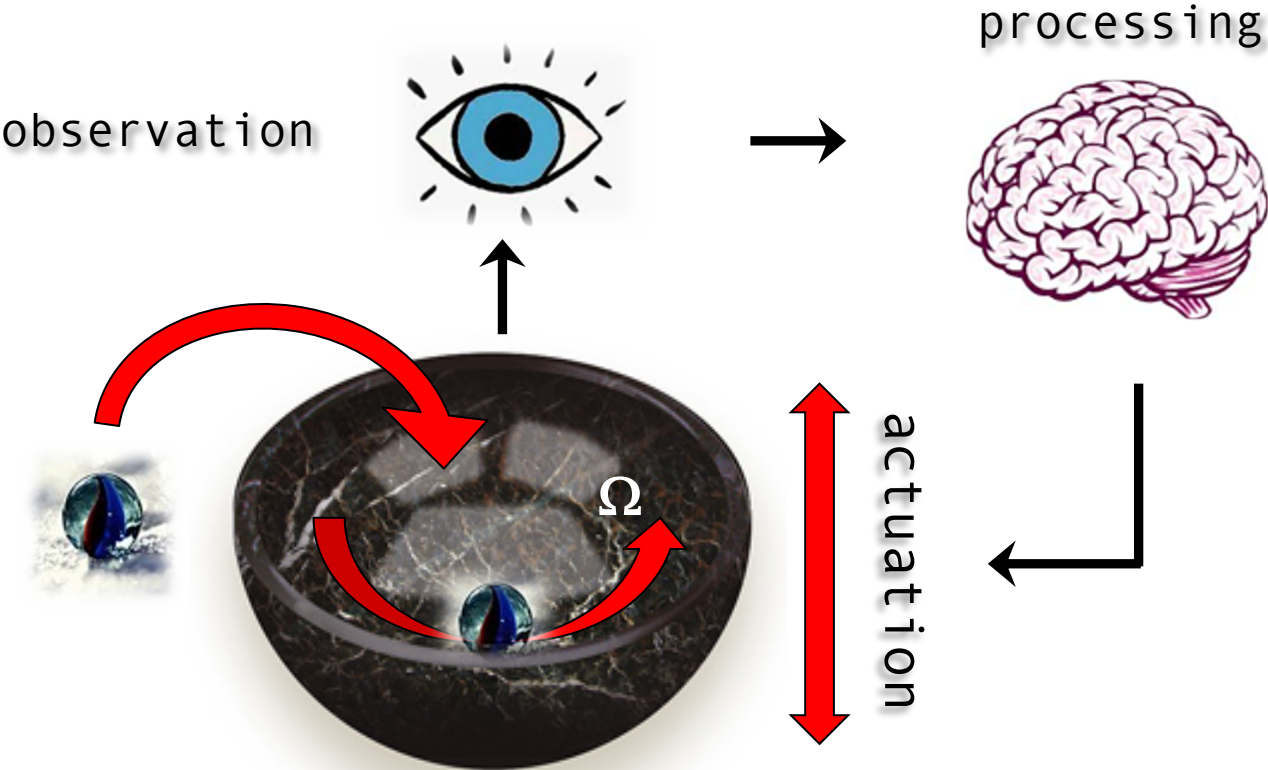
Feedback Cooling of a Single Neutral Atom

Markus Koch,^{1,*} Christian Sames,¹ Alexander Kubanek,¹ Matthias Apel,¹ Maximilian Balbach,¹

Alexei Ourjoumtsev,^{1,†} Pepijn W. H. Pinkse,² and Gerhard Rempe¹



FEEDBACK CONTROL

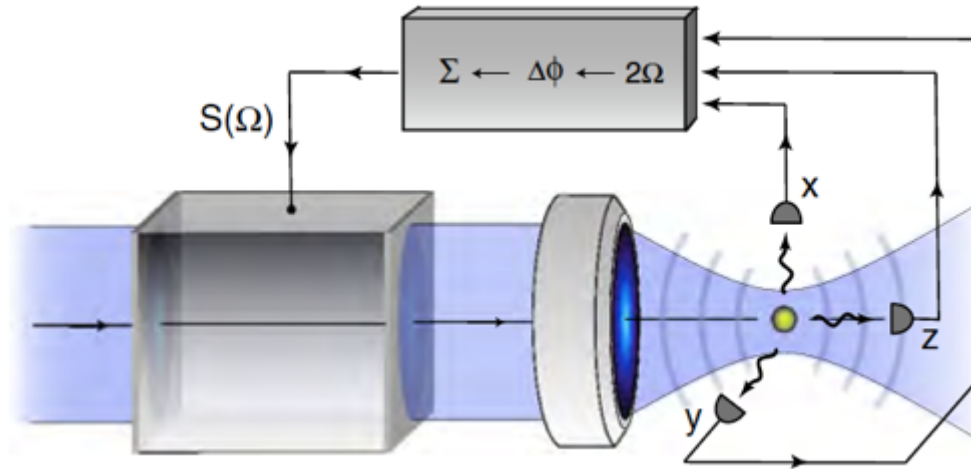


PARAMETRIC FEEDBACK COOLING

$$\ddot{x}(t) + \gamma \dot{x}(t) + \Omega_0^2 x(t) = (1/m) [F_{\text{fluct}}(t) + F_{\text{opt}}(t)]$$

$$\hookrightarrow \Delta k_{\text{trap}}(t) x(t)$$

$$\downarrow x(t)\dot{x}(t)$$



Parametric feedback (2012) :

PRL 109, 103603 (2012)

PHYSICAL REVIEW LETTERS

week ending
7 SEPTEMBER 2012

Subkelvin Parametric Feedback Cooling of a Laser-Trapped Nanoparticle

Jan Gieseler,¹ Bradley Deutsch,³ Romain Quidant,^{1,2} and Lukas Novotny^{3,4}

Backaction limited measurement (2016) :

PRL 116, 243601 (2016)

PHYSICAL REVIEW LETTERS

week ending
17 JUNE 2016



Direct Measurement of Photon Recoil from a Levitated Nanoparticle

Vijay Jain,^{1,2} Jan Gieseler,¹ Clemens Moritz,³ Christoph Dellago,³ Romain Quidant,^{4,5} and Lukas Novotny^{1,*}

Optimal control (2019) :

PHYSICAL REVIEW LETTERS 122, 223601 (2019)

Cold Damping of an Optically Levitated Nanoparticle to Microkelvin Temperatures

Felix Tebbenjohanns, Martin Frimmer, Andrei Militaru, Vijay Jain, and Lukas Novotny

Optimal detection (2019) :

PHYSICAL REVIEW A 100, 043821 (2019)

Optimal position detection of a dipolar scatterer in a focused field

Felix Tebbenjohanns,¹ Martin Frimmer, and Lukas Novotny

Sideband asymmetry (2020) :

PHYSICAL REVIEW LETTERS **124**, 013603 (2020)

Motional Sideband Asymmetry of a Nanoparticle Optically Levitated in Free Space

Felix Tebbenjohanns, Martin Frimmer, Vijay Jain, Dominik Windey, and Lukas Novotny

Groundstate (2021):

Real-time optimal quantum control of mechanical motion at room temperature

Lorenzo Magrini¹✉, Philipp Rosenzweig², Constanze Bach¹, Andreas Deutschmann-Olek², Sebastian G. Hofer¹, Sungkun Hong^{3,4}, Nikolai Kiesel¹, Andreas Kugi^{2,5} & Markus Aspelmeyer^{1,6}✉

Nature | Vol 595 | 15 July 2021 | **373**

Quantum control of a nanoparticle optically levitated in cryogenic free space

Felix Tebbenjohanns^{1,3}, M. Luisa Mattana^{1,3}, Massimiliano Rossi^{1,3}, Martin Frimmer¹ & Lukas Novotny^{1,2}✉

378 | Nature | Vol 595 | 15 July 2021



COOLING DYNAMICS

Equation of motion : $\ddot{y} + \gamma \dot{y} + \Omega_0^2 y = \frac{1}{m} F_{\text{fluct}}(t)$

feedback gain

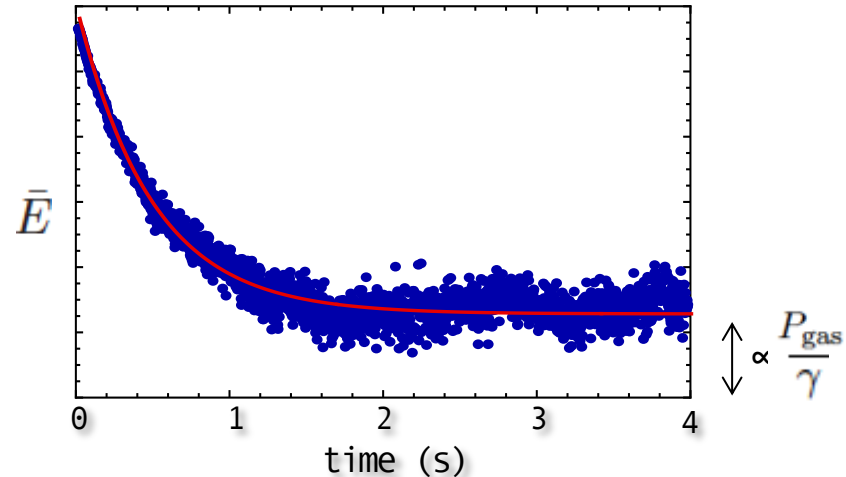
gas pressure

$$S_F(\Omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \langle F_{\text{fluct}}(t) F_{\text{fluct}}(t+t') \rangle e^{i\Omega t'} dt' \propto P_{\text{gas}}$$

Energy : $\frac{d}{dt} \bar{E}(t) = -\gamma \bar{E}(t) + \frac{\pi}{m} S_F$

↓ cooling ↓ heating

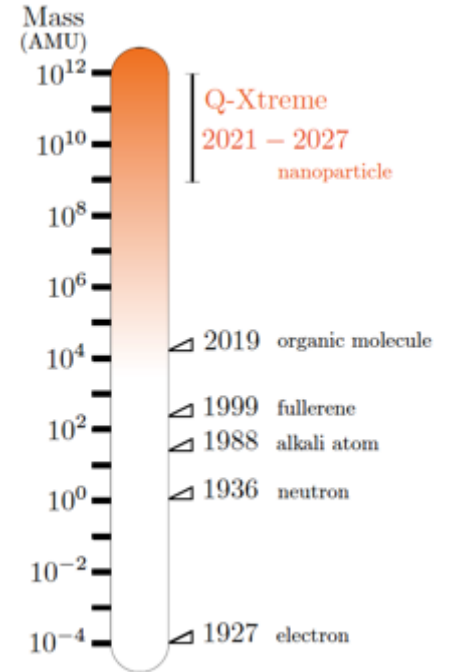
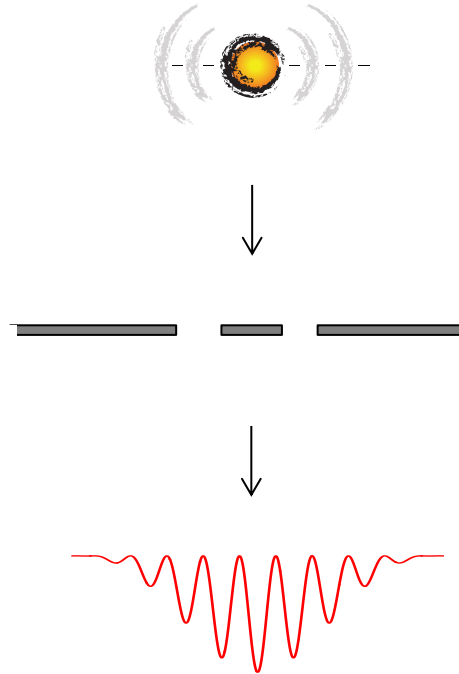
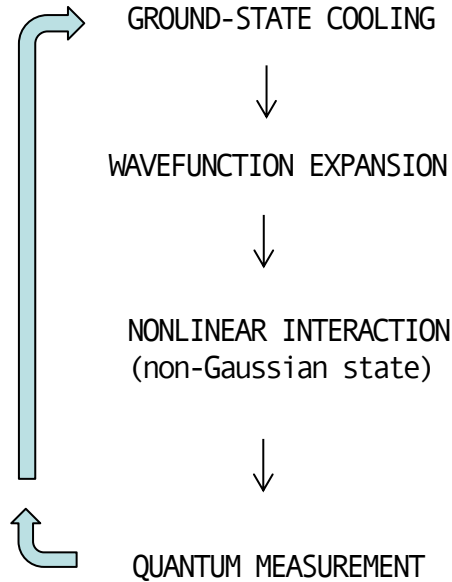
$$\rightarrow \bar{E}(t) = E_{\infty} + [\bar{E}(0) - E_{\infty}] e^{-\gamma t}$$



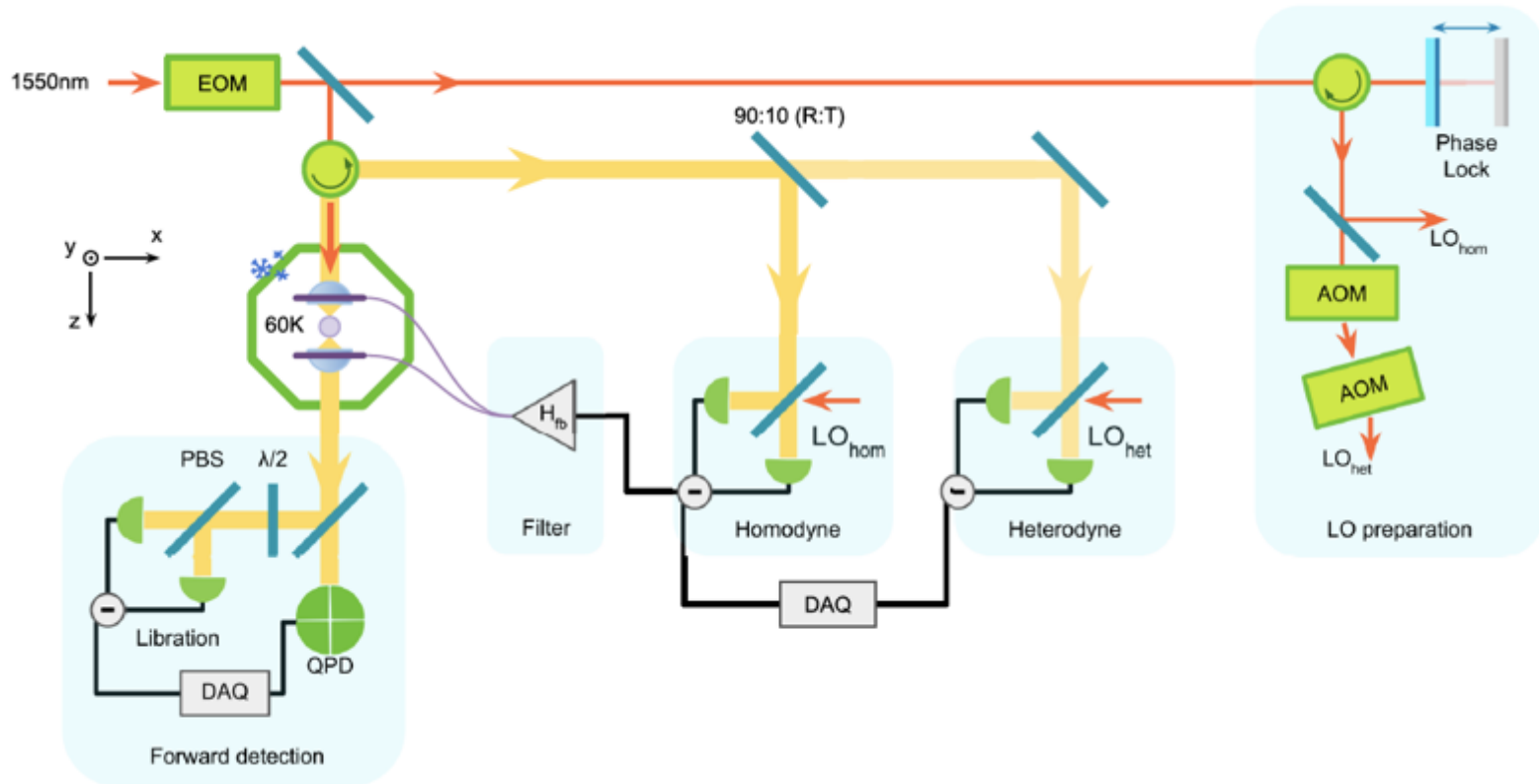
OUTLINE

- 1: INTRODUCTION (A PERSONAL STORY)
- 2: Q-XTREME & GROUND-STATE**
- 3: STATE EXPANSION
- 4: OUTLOOK

GENERATING MACROSCOPIC QUANTUM SUPERPOSITIONS

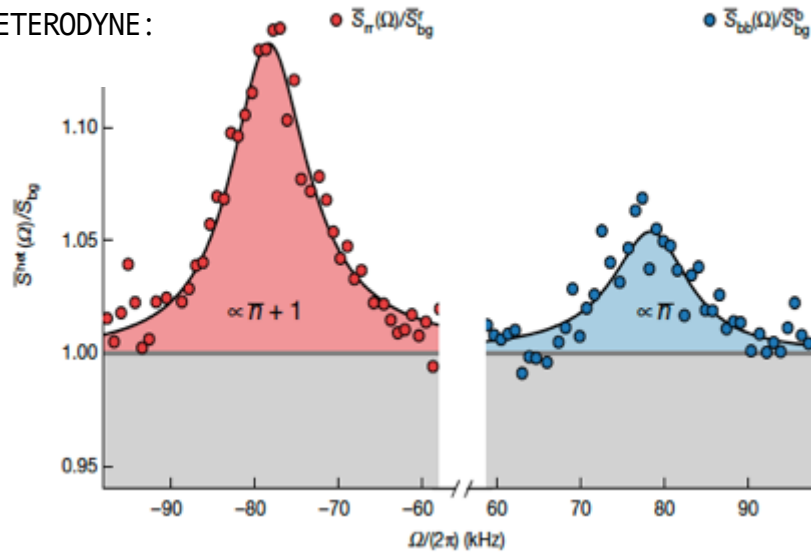


GROUND-STATE COOLING



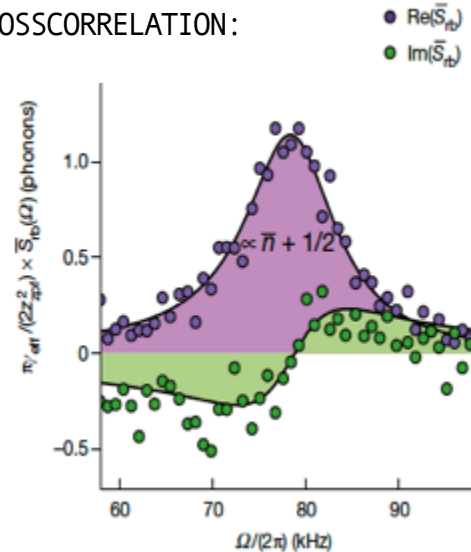
GROUND-STATE COOLING IN CRYOGENIC FREE SPACE

OUT-OF-LOOP
HETERODYNE:



$$\bar{n} = 0.66 \pm 0.08$$

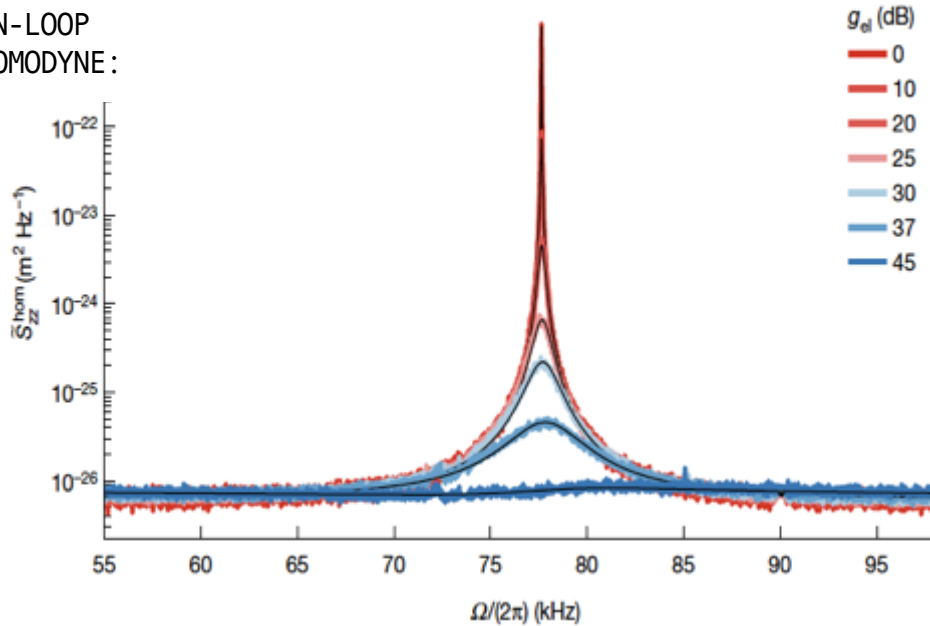
OUT-OF-LOOP
CROSSCORRELATION:



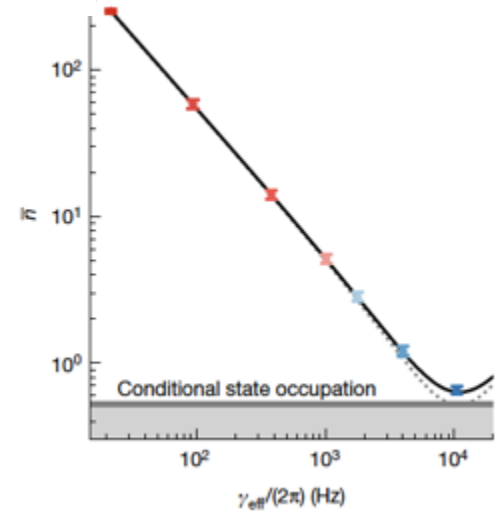
$$\bar{n} = 0.64 \pm 0.09$$

GROUND-STATE COOLING IN CRYOGENIC FREE SPACE

IN-LOOP
HOMODYNE :

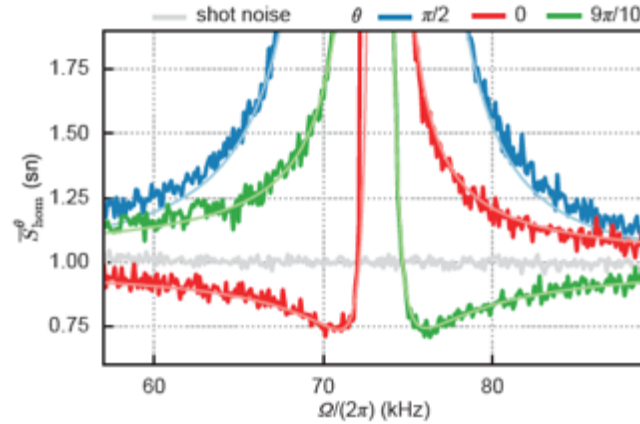
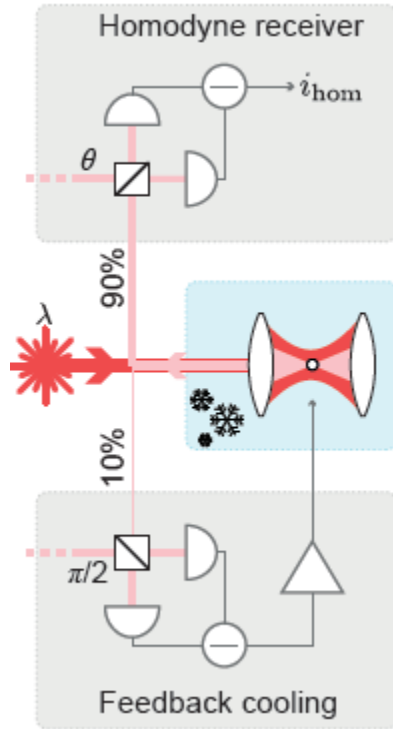


$$\eta_{\text{meas}} = \Gamma_{\text{meas}} / \Gamma_{\text{tot}} = 0.24 \pm 0.02$$



$$\bar{n} = 0.65 \pm 0.04$$

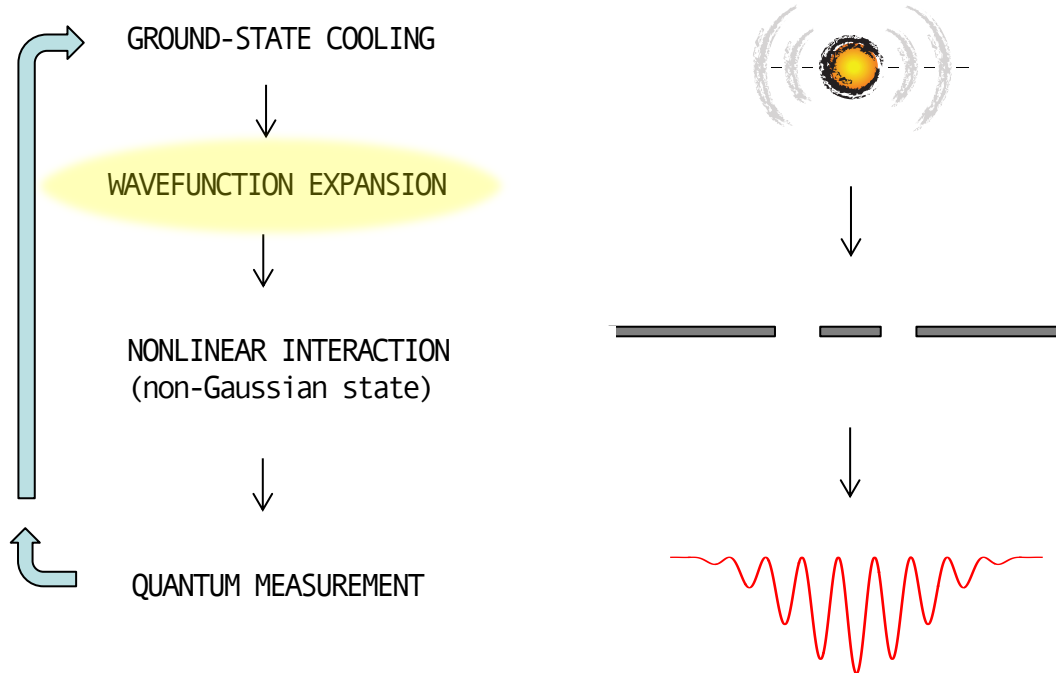
PONDEROMOTIVE SQUEEZING



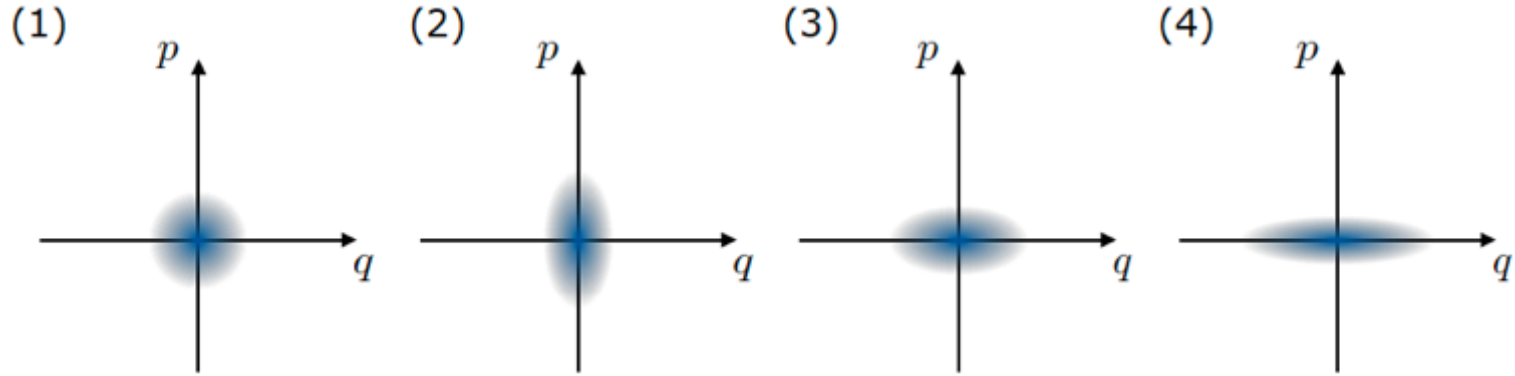
$$\bar{S}_{PP} = 1 + \underbrace{\bar{S}_{\text{imp}}^\theta}_{8\Gamma_{\text{meas}} (\sin \theta)^2} |m\Omega_0\chi|^2 \underbrace{\bar{S}_{FF}^{\text{tot}}}_{2\Gamma_{\text{tot}}} - 2 \text{Re}\{ \underbrace{(m\Omega_0\chi)}_{2\Gamma_{\text{meas}} \sin(2\theta)} \bar{S}_{\text{corr}}^\theta \}$$

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GENERATING MACROSCOPIC
QUANTUM SUPERPOSITIONS

WAVEFUNCTION EXPANSION



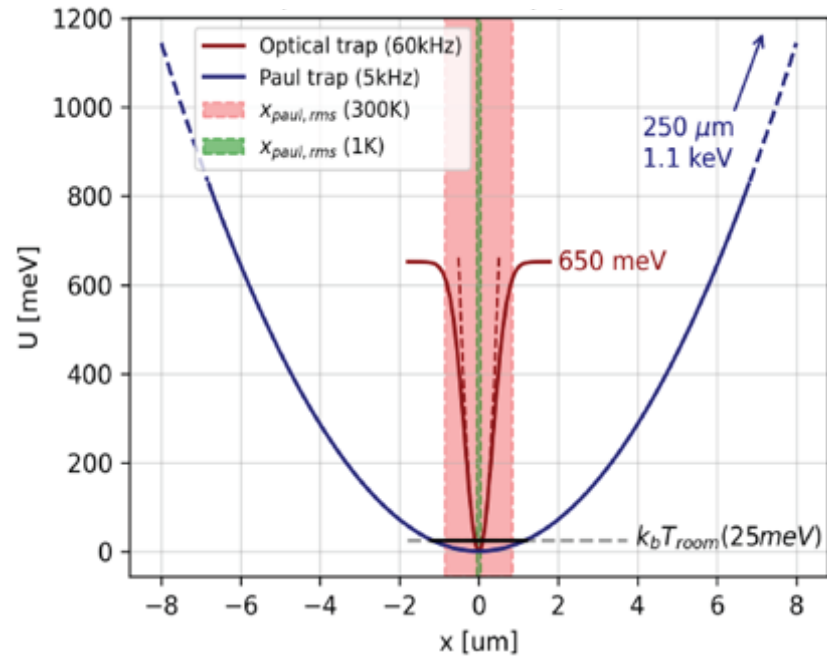
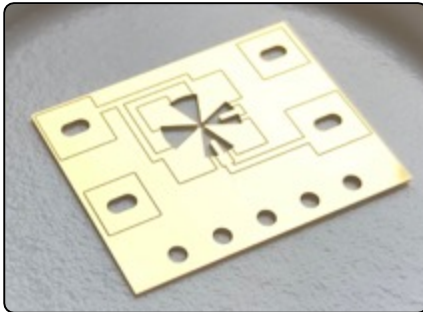
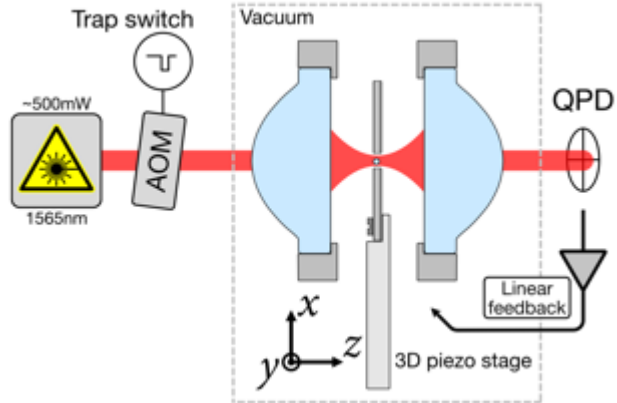
1. Initialization: $|0\rangle$
2. Switch resonance frequency from Ω_0 to Ω_1 : $S|0\rangle$
3. Rotate state by a quarter (of the new) period: $e^{-\frac{i\pi}{2}b^\dagger b}S|0\rangle$
4. Switch resonance frequency back to Ω_0 : $\underbrace{S^\dagger e^{-\frac{i\pi}{2}b^\dagger b} S}_{S^2}|0\rangle$

Final squeezing $s^2 = \left(\frac{\Omega_0}{\Omega_1}\right)^2$

HYBRID rf-OPTICAL TRAP

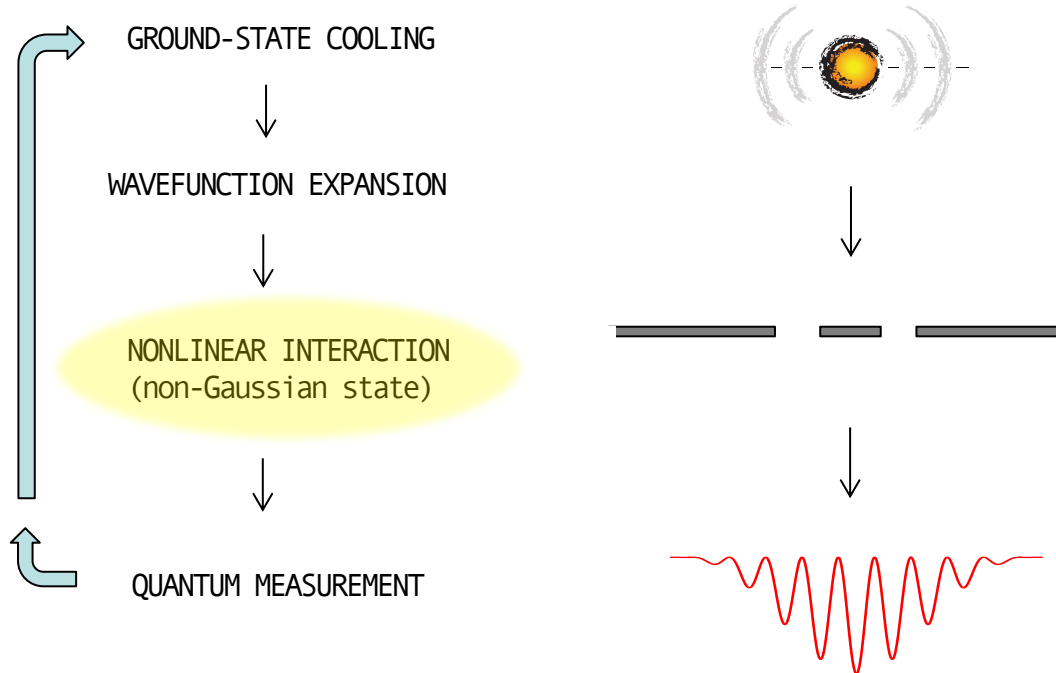


Eric Bonvin

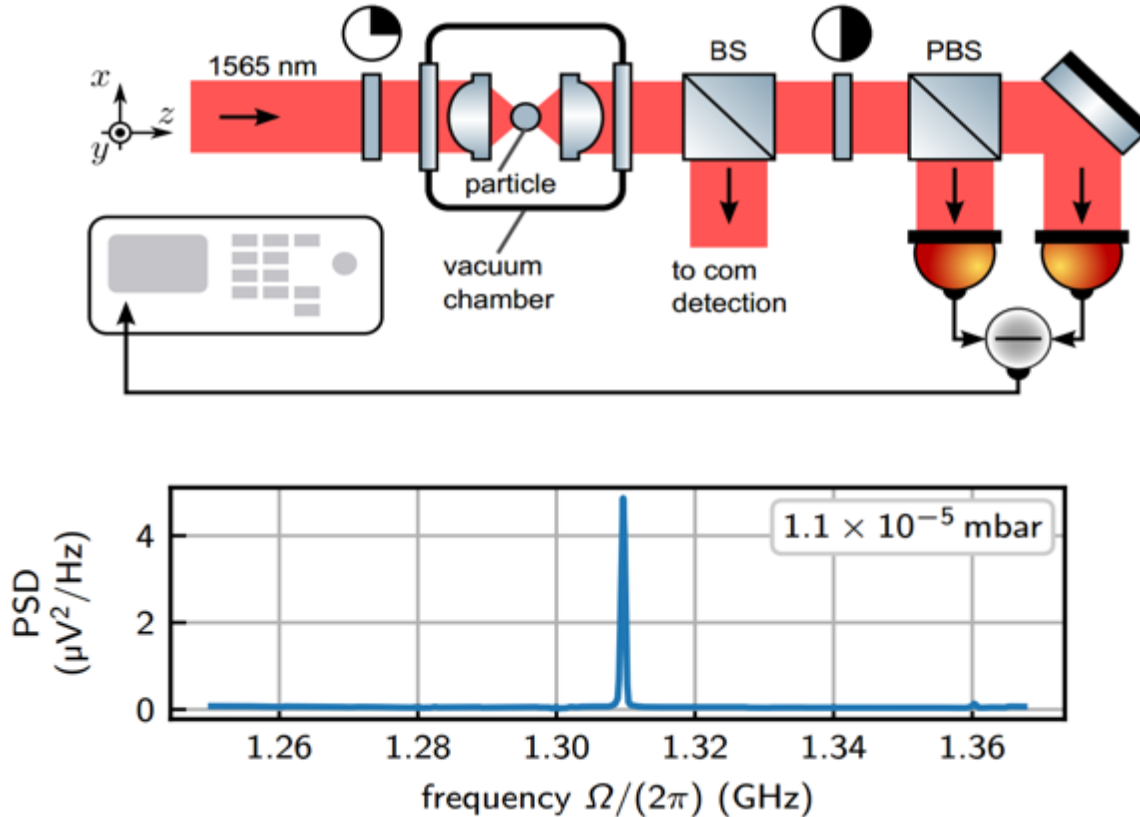


OUTLINE

- 1: INTRODUCTION (A PERSONAL STORY)
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GENERATING MACROSCOPIC
QUANTUM SUPERPOSITIONS

ROTATIONS



Joanna Zielinska

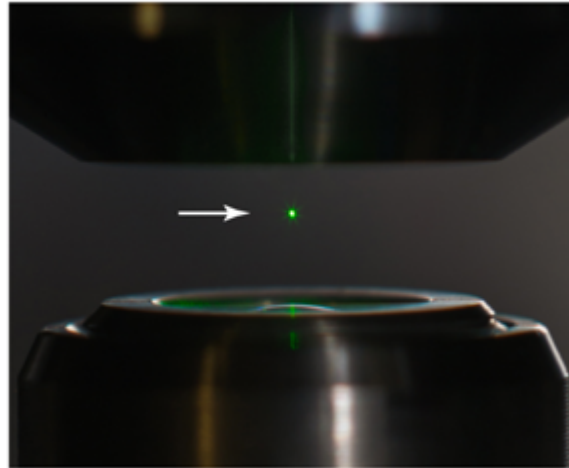
c. f. work by:
 M. Arndt
 J. Millen
 K. Dholakia
 P. Zemanek
 T. Li
 D. Moore
 ...

INERTIAL SENSING



European
Commission

Horizon 2020
European Union funding
for Research & Innovation



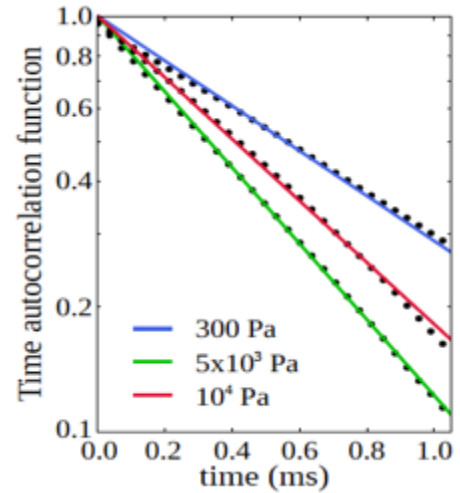
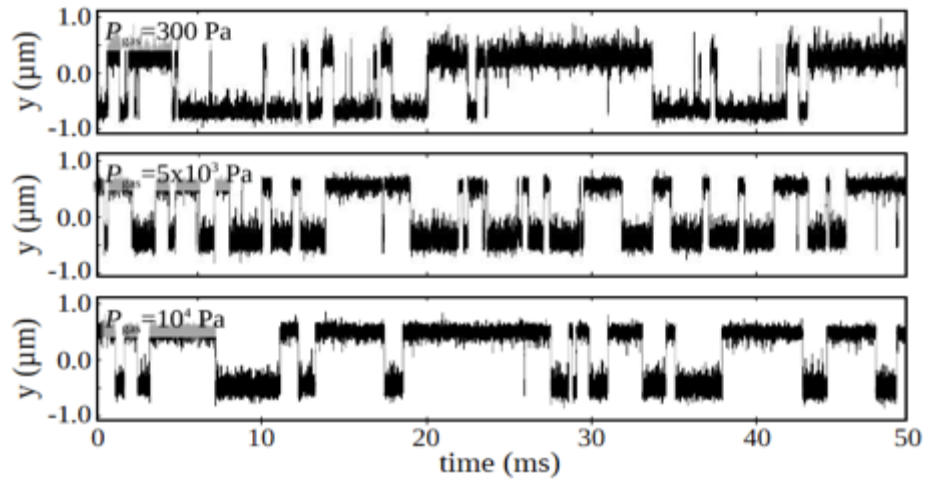
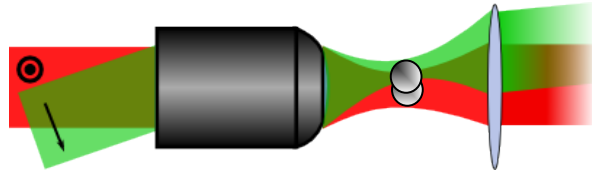
accelerometers → $\text{ng}/\text{Hz}^{1/2}$

gyroscopes → $\mu\text{deg}/\text{hr}$

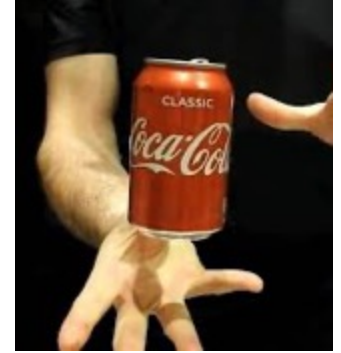
iXblue



KINETICS



SIMULATION



$$\ddot{x} + \gamma \dot{x} + \Omega_0^2 x = \delta F(t)/m \quad (\text{equilibrium dynamics})$$

$$\ddot{x} + \gamma \dot{x} + \Omega_0^2 x [1 + \Omega_0^{-1} \eta x \dot{x}] = \delta F(t)/m \quad (\text{parametric feedback})$$

$$\ddot{x} + \gamma \dot{x} + \Omega_0^2 x [1 + \Omega_0^{-1} \eta x \dot{x} + \epsilon \cos(\Omega_m t)] = \delta F(t)/m \quad (\text{parametric modulation})$$

$$\ddot{x} + \gamma \dot{x} + \Omega_0^2 x [1 + \Omega_0^{-1} \eta x \dot{x} + \epsilon \cos(\Omega_m t) + \xi x^2] = \delta F(t)/m \quad (\text{Duffing nonlinearity})$$

$$\ddot{x} + \gamma \dot{x} + \Omega_0^2 x [1 + \Omega_0^{-1} \eta x \dot{x} + \epsilon \cos(\Omega_m t) + \xi x^2] = \delta F(t)/m + F_{\text{drive}}(t)/m \quad (\text{external drive})$$

$$\ddot{x} + \gamma \dot{x} + \Omega_0^2 x [1 + \Omega_0^{-1} \eta x \dot{x} + \epsilon \cos(\Omega_m t) + \xi x^2] + \delta \cos(\omega t) y = \delta F(t)/m + F_{\text{drive}}(t)/m \quad (\text{mode coupling})$$

- ro-vibrational coupling, non-equilibrium dynamics, cross-Kerr nonlinearities ...
- multimode coupling (+rotations), state-dependent noise, chaos, topological physics ...
- non-Hermitian dynamics, PT-symmetric processes, ...

SUMMARY

- Active & passive feedback cooling
- Parametric feedback and cold damping
- Quantum control
- Ultrahigh force sensitivity
- Free-fall (sensing of static forces)
- Nonequilibrium dynamics
- Interactions with surfaces (and other particles)
- GHz rotations
- Internal degrees of freedom

Nanomagnetic Imaging using Scanning Probe Microscopy Techniques

PhD Course, EPFL, 2022

Sensitivity

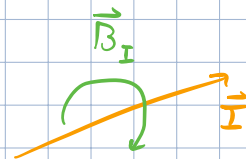
To evaluate sensitivity: **Signal** - to - **noise**

Let's take two idealized signals:

- a line of current \vec{I}
- a magnetic moment \vec{m}

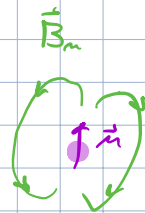
- Current:

$$\vec{B}_I = \frac{\mu_0 \vec{I} \times \vec{r}}{2\pi r^2}$$



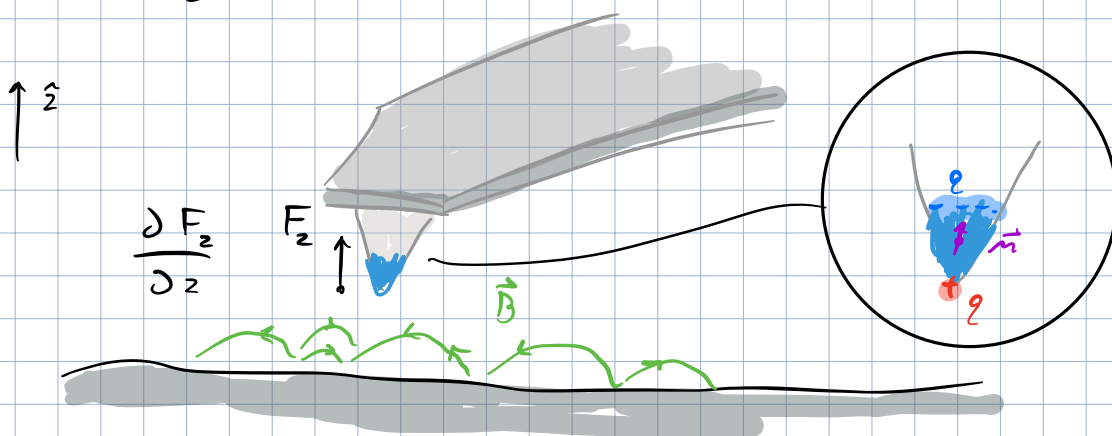
- moment:

$$\vec{B}_m = \frac{\mu_0}{4\pi r^3} \left(\frac{3(\vec{m} \cdot \vec{r})\vec{r}}{r^2} - \vec{m} \right)$$



MFM

- **Signal**



$$F_z = \rho \vec{B} \cdot \hat{z} + \vec{\tau} (\vec{\mu} \cdot \vec{B}) \cdot \hat{z}$$

↘ monopole
↘ dipole

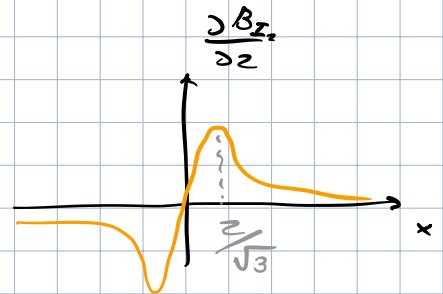
If we assume a monopole tip and a measurement of force gradients (ΔF):

$$\frac{\partial F_z}{\partial z} = \rho \frac{\partial B_z}{\partial z} \quad \therefore \quad \frac{\partial B_z}{\partial z} = \frac{1}{\rho} \frac{\partial F_z}{\partial z}$$

The maximum signal at a given height z that we can measure for a line of current:

$$\frac{\partial}{\partial x} \left(\frac{\partial B_{Iz}}{\partial z} \right) = 0$$

$$x = -\frac{z}{\sqrt{3}}, \frac{z}{\sqrt{3}}$$



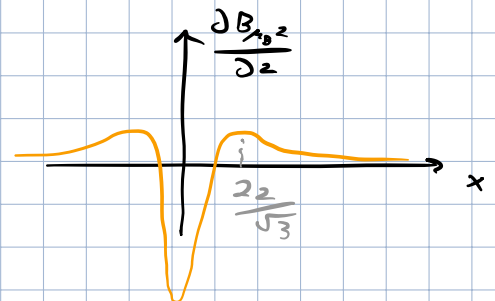
$$\left(\frac{\partial B_{Iz}}{\partial z} \right)_{\max} = \frac{3\sqrt{3} \mu_0 I}{16\pi z^2}$$

$$\left[\frac{T}{m} \right]$$

Similarly for a μ_B of magnetic moment:

$$\frac{\partial}{\partial x} \left(\frac{\partial B_{\mu_B z}}{\partial z} \right) = 0$$

$$x = -\frac{2z}{\sqrt{3}}, 0, \frac{2z}{\sqrt{3}}$$



$$\left(\frac{\partial B_{\mu_B z}}{\partial z} \right)_{\max} = \frac{3\mu_0 \mu_B}{2\pi z^2}$$

$$\left[\frac{T}{m} \right]$$

• Noise

The ultimate noise limit is from the thermal motion of the cantilever:

$$S_F = 4k_B T \Gamma \quad \leftarrow \text{Fluctuation-Dissipation Theorem}$$

This implies a thermal force noise amplitude that sets a minimum measurable force:

$$F_{\min} = \sqrt{4k_B T \Gamma}$$

For measurements of force gradients done by oscillating the cantilever by z_{rms} and monitoring its resonant frequency, we have:

$$\left(\frac{\partial F}{\partial z} \right)_{\min} = \frac{1}{z_{\text{rms}}} \sqrt{4k_B T \Gamma}$$

→ 30 $\frac{\text{N}}{\text{m}} \sqrt{\text{Hz}}$
@ 4K

$$\therefore \left(\frac{\partial B_z}{\partial z} \right)_{\min} = \frac{1}{2 z_{\text{rms}}} \sqrt{4k_B T \Gamma} \quad \left[\frac{\text{T}}{\text{m}} \sqrt{\text{Hz}} \right]$$

We can then see the sensitivity to I or μ_B by writing:

Current Sens.

$$\frac{\left(\frac{\partial B_z}{\partial z}\right)_{\min}}{\left(\frac{\partial B_{Iz}}{\partial z}\right)_{\max}} \cdot I \propto z^2 \left[\frac{A}{\sqrt{Hz}} \right] \rightarrow \frac{\mu_A}{\sqrt{Hz}} @ 50 \text{ nm}$$

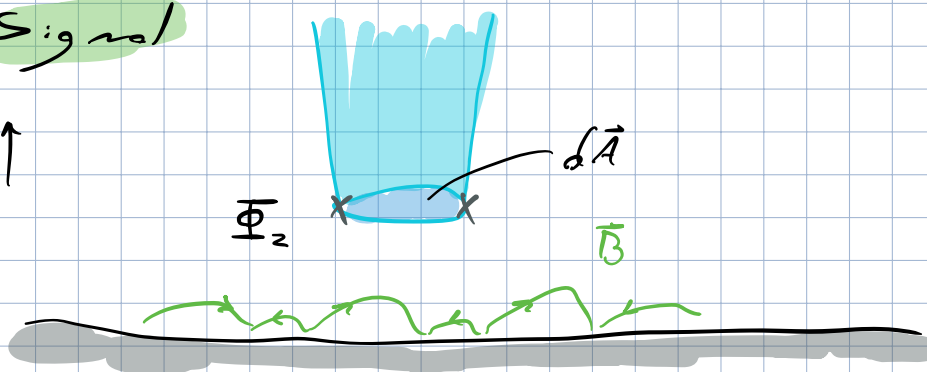
Moment Sens.

$$\frac{\left(\frac{\partial B_z}{\partial z}\right)_{\min}}{\left(\frac{\partial B_{\mu_B z}}{\partial z}\right)_{\max}} \cdot \mu_B \propto z^4 \left[\frac{\mu_B}{\sqrt{Hz}} \right] \rightarrow \frac{10^3 \mu_B}{\sqrt{Hz}} @ 50 \text{ nm}$$

SSM

• Signal

$z \uparrow$



$$\Phi_z = \int \vec{B} \cdot d\vec{A}$$

If we now calculate the flux directly above a μ_B of moment:

$$\left(\Phi_{\mu_B z} \right)_{\max} = \frac{\mu_0 \mu_B R^2}{2(z^2 + R^2)^{3/2}} \quad [\tau \cdot m^2 = W_b]$$

loop radius

Noise

There are several sources of noise:

- Johnson noise
- shot noise
- $1/f$ noise ← at low freq
- quantum noise $\rightarrow \Phi_0 = \sqrt{k L}$

states of the qut are $\sim 4 \times$ this limit Loop inductance

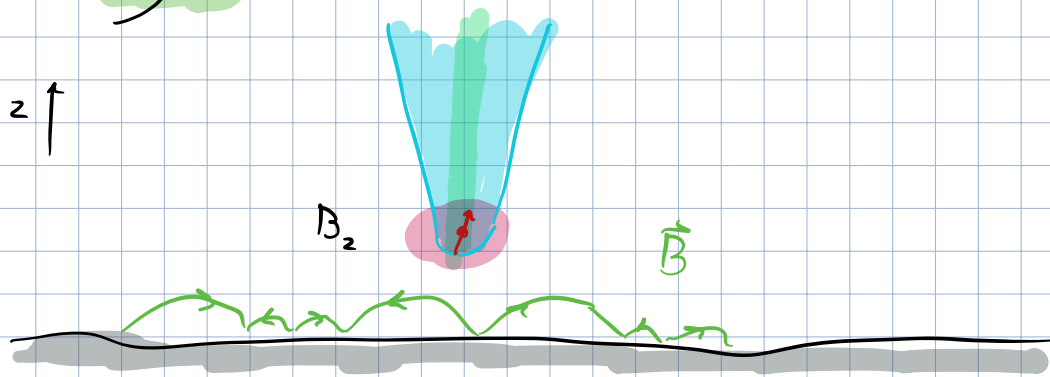
$$\therefore \left(\Phi_z \right)_{\min} = \Phi_{\text{noise}} \rightarrow 50 \sim \frac{\Phi_0}{\sqrt{Hz}}$$

Sensitivity:

Current Sens.	$\frac{\left(\Phi_z \right)_{\min}}{\left(\Phi_{Iz} \right)_{\max}} \cdot I$	$\left[\frac{A}{\sqrt{Hz}} \right]$	$\rightarrow 10 \frac{nA}{\sqrt{Hz}} @ 50 \text{ nA}$
Moment Sens.	$\frac{\left(\Phi_z \right)_{\min}}{\left(\Phi_{\mu_B z} \right)_{\max}} \cdot \mu_B \propto 2^3$	$\left[\frac{\mu_B}{\sqrt{Hz}} \right]$	$\rightarrow \frac{\mu_B}{\sqrt{Hz}} @ 50 \text{ nA}$

SNVM

• Signal



By measuring the NV splitting, we measure the magnetic field along the NV axis:

$$B_z = \vec{B} \cdot \hat{z}$$

$$(B_{Iz})_{\max} = \frac{\mu_0 I}{4\pi z} \quad [T]$$

$$(B_{Mz})_{\max} = \frac{\mu_0 M_B}{2\pi z^3} \quad [T]$$

• **Noise**

SNVM is typically limited by photon shot noise from the optical read-out.

Minimum measurable field can be written as:

$$(B_z)_{min} = \frac{1}{\gamma \Sigma \sqrt{I_0 \tau_{avg} T_2}}$$

Annotations for the equation above:

- 1: optical contrast
- γ : gyromagnetic ratio
- Σ : count rate
- $\sqrt{I_0 \tau_{avg} T_2}$: integration
- T_2 : dephasing

→ 100 nT / $\sqrt{\text{Hz}}$

Sensitivity:

Current Sens.	$\frac{(B_z)_{min}}{(B_{Iz})_{max}} \cdot I \propto 2$	$\left[\frac{A}{\sqrt{\text{Hz}}} \right]$	→ 10 nA / $\sqrt{\text{Hz}}$ @ 25 nm
Moment Sens.	$\frac{(B_z)_{min}}{(B_{\mu_2})_{max}} \cdot \mu_B \propto 2^3$	$\left[\frac{\mu_B}{\sqrt{\text{Hz}}} \right]$	→ 100 / $\sqrt{\text{Hz}}$ @ 25 nm

Reconstruction of \vec{I} & \vec{m} from \vec{B}

Biot - Savart :

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}') \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} d^3 r'$$

For current density $\vec{J} = J_x \hat{x} + J_y \hat{y}$

or magnetization $\vec{m} = M_2 \hat{z}$ in 2D

we can write this in k -space :

$$\tilde{B}_z(k_x, k_y, z) = i \underbrace{\frac{1}{2} \mu_0 d e^{-kz}}_{g(k, z)} \left[\frac{k_y}{k} \tilde{J}_x(k_x, k_y) - \frac{k_x}{k} \tilde{J}_y(k_x, k_y) \right]$$

$$\text{w/ } k = \sqrt{k_x^2 + k_y^2}$$

$$\text{and } d \ll z$$

(film thickness)

Continuity equation : $\vec{\nabla} \cdot \vec{J} = 0$

$$\rightarrow k_x \tilde{J}_x + k_y \tilde{J}_y = 0$$

$$\tilde{J}_y = - \frac{k_x}{k_y} \tilde{J}_x$$

Together :

$$\tilde{B}_z = i g \frac{\tilde{J}_x}{k} \left(k_y + \frac{k_x^2}{k_y} \right) = i g \frac{\tilde{J}_x}{k_y} k$$

$$\tilde{J}_x = - \frac{i k_y \tilde{B}_2}{k_g}$$

$$\tilde{J}_y = \frac{i k_x \tilde{B}_2}{k_g}$$

Magnetization :

$$\vec{J} = \vec{\nabla} \times \vec{M}$$

$$\hookrightarrow \therefore J_x = \frac{\partial M_z}{\partial y}, \quad J_y = - \frac{\partial M_z}{\partial x}$$

$$\tilde{J}_x = -i k_y \tilde{M}_z, \quad \tilde{J}_y = i k_x \tilde{M}_z$$

$$\therefore \tilde{M}_z = \frac{\tilde{B}_2}{k_g}$$

Current
density

Magnetization

$$\tilde{B}_2 = -i \frac{1}{2} \mu_0 \delta e^{-kz} \frac{k}{k_x} \tilde{J}_y$$

$$\tilde{B}_2 = \frac{1}{2} \mu_0 \delta e^{-kz} k \tilde{M}_z$$

Derivative along z :

$$\frac{\partial \tilde{B}_2}{\partial z} \propto e^{-kz} \frac{k^2}{k_x}$$

$$\frac{\partial \tilde{B}_2}{\partial z} \propto e^{-kz} k^2$$

$$k \propto k_x \propto \frac{1}{\lambda}$$

Feature size

Normalized to distance: $\frac{z}{\lambda}$

$$\tilde{B}_2 \propto e^{-\frac{z}{\lambda}}$$

$$\tilde{B}_2 \propto \frac{1}{2} \left(\frac{z}{\lambda}\right) e^{-\frac{z}{\lambda}}$$

$$\frac{\partial \tilde{B}_2}{\partial z} \propto \frac{1}{2} \left(\frac{z}{\lambda}\right) e^{-\frac{z}{\lambda}}$$

$$\frac{\partial \tilde{B}_2}{\partial z} \propto \frac{1}{2^2} \left(\frac{z}{\lambda}\right)^2 e^{-\frac{z}{\lambda}}$$